First-passage resetting (and some other first-passage problems)

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First-passage resetting

Optimization in first-passage resetting

Multi-particle first-passage resetting

A first-passage problem for the Brownian supremum

A first-passage problem for the Brownian range

Topics in this talk include:

- ▷ stochastic processes specifically Brownian motion
- ▷ first-passage problems [see eg A Guide to First-Passage Processes, Redner 2001]
- ▷ resetting of a stochastic process:
 - ♦ restart at regular fixed times [textbook, see eg Ex. 22 in Grimmett & Stirzaker]
 - restart at random times indep. of the process:
 eg stochastic resetting with exp. dist. times admits optimal rate
 [see Evans & Majumdar 2011, and review by Evans, Majumdar, Schehr 2020]
 - restart at random times dep. on the process: *elementary/instantaneous return* process [Feller 1953, Sherman 1957], Brownian motion with rebirth [Grigorescu & Kang 2007] first-passage resetting [de Bruyne, R-F, Redner 2020]
- ▷ path transformations i.e. bijections between sets of sample paths

First-passage resetting

First-passage resetting in Brownian motion: semi-infinite geometry



 $\triangleright\,$ Brownian particle starting at the origin, with diffusion constant D

- \triangleright when it reaches $L \longrightarrow$ instantaneously reset to the origin
- \triangleright and so on successive "first"-passage/reset times t_1, t_2, \ldots

Pdf for *n*th reset time? Pdf for position at *t*? Number of resets? (recall that average time between two resets is infinite)

- \triangleright Define: $F_n(L, t) = pdf$ for the n^{th} reset to occur at time t.
- ▷ One has the renewal equation:

$$F_n(L,t) = \int_0^t dt' F_{n-1}(L,t') F_1(L,t-t'), \quad n > 1.$$

Convolution structure \longrightarrow Laplace transform:

$$\widetilde{F}_n(L,s) = \left[\widetilde{F}_1(L,s)\right]^n = \left[e^{-L\sqrt{s/D}}\right]^n = e^{-nL\sqrt{s/D}}$$

$$F_n(L,t) = \frac{n L}{\sqrt{4\pi D t^3}} e^{-n^2 L^2/4Dt}$$

 \ominus pdf for n^{th} reset at t = pdf for 1^{st} passage at n L at t

First-passage resetting in Brownian motion: pdf for the position at t



P(x, t) dx = Prob (particle in [x, x + dx] at time t)

 \triangleright Introduce the propagator with absorption at *L*,

$$G(x, L, t) = \left[e^{-x^2/4Dt} - e^{-(x-2L)^2/4Dt}\right]/\sqrt{4\pi Dt}$$

▷ Then one has the *forward* renewal equation:

$$P(x,t) = G(x,L,t) + \sum_{n\geq 1} \int_0^t dt' F_n(L,t') G(x,L,t-t'),$$

▷ or equivalently the *backward* renewal equation:

$$P(x,t) = G(x,L,t) + \int_0^t dt' F_1(L,t') P(x,t-t').$$

Again, convolution structure \longrightarrow Laplace transform:

$$\widetilde{P}(y,s) = rac{\widetilde{G}(y,y_L,s)}{1-\widetilde{F}_1(y_L,s)} = rac{1}{\sqrt{4Ds}} rac{\left[e^{-|y|}-e^{-|y-2y_L|}
ight]}{1-e^{-y_L}},$$

with reduced variables $y = x\sqrt{s/D}$ and $y_L = L\sqrt{s/D}$.

2 distinct cases -
$$\begin{cases} 0 \le y \le y_L & \text{i.e. } 0 \le x \le L \\ y < 0 & \text{i.e. } x < 0 \end{cases}$$

First-passage resetting in Brownian motion: pdf for the position at t

Computing P(x, t) – when $0 \le x \le L$ i.e. $0 \le y \le y_L$

$$\widetilde{P}(y,s) = \frac{1}{\sqrt{4Ds}} \left[e^{-y} - e^{-(2y_L - y)} \right] \sum_{n \ge 0} e^{-ny_L} = \frac{1}{\sqrt{4Ds}} \sum_{n \ge 0} \left[e^{-(y + ny_L)} - e^{-[(n+2)y_L - y]} \right],$$

from which

$$P(x,t) = \frac{1}{\sqrt{4\pi Dt}} \sum_{n\geq 0} \left[e^{-(x+nL)^2/4Dt} - e^{-[x-(n+2)L]^2/4Dt} \right].$$

In the long-time limit, $t \gg 1$

$${\sf P}(x,t)\simeq rac{1}{\sqrt{\pi Dt}}\,rac{L-x}{L}$$

 \ominus balance between diffusive flux exiting at x = L and re-injected at x = 0.

Computing P(x, t) – when x < 0 i.e. y < 0

$$\widetilde{P}(y,s) = \frac{1}{\sqrt{4Ds}} \left[\frac{e^{y} - e^{y-2y_L}}{1 - e^{-y_L}} \right] = \frac{1}{\sqrt{4Ds}} \left[e^{y} + e^{(y-y_L)} \right],$$

from which

$$P(x,t) = \frac{1}{\sqrt{4\pi Dt}} \left[e^{-x^2/4Dt} + e^{-(x-L)^2/4Dt} \right].$$

 \hookrightarrow i.e. superposition of paths from 0 and paths from L... Interpretation?

Computing P(x, t) – when x < 0 i.e. y < 0

$$\widetilde{P}(y,s) = \frac{1}{\sqrt{4Ds}} \left[\frac{e^{y} - e^{y-2y_L}}{1 - e^{-y_L}} \right] = \frac{1}{\sqrt{4Ds}} \left[e^{y} + e^{(y-y_L)} \right],$$

from which

$$P(x,t) = \frac{1}{\sqrt{4\pi Dt}} \left[e^{-x^2/4Dt} + e^{-(x-L)^2/4Dt} \right].$$

 \hookrightarrow i.e. superposition of paths from 0 and paths from L – easy with path transformation

First-passage resetting in Brownian motion: pdf for the position at t





First-passage resetting in Brownian motion: number of resets

 \triangleright Define: $Q_n(L, t) = Prob(exactly n resets occur up to time t).$

$$Q_n(L,t) = \int_0^t dt' \left[F_n(L,t') - F_{n+1}(L,t') \right] = \operatorname{erf}\left(\frac{(n+1)L}{\sqrt{4Dt}}\right) - \operatorname{erf}\left(\frac{nL}{\sqrt{4Dt}}\right)$$

 \triangleright Backward renewal equation for the average number of resets $\mathcal{N}(t)$:

$$\mathcal{N}(t) = \int_0^t dt' F_1(L,t') (1 + \mathcal{N}(t-t')) \,.$$

▷ Laplace transforming:

$$\widetilde{\mathcal{N}}(s) = \frac{\widetilde{F}_{1}(L,s)}{s\left[1 - \widetilde{F}_{1}(L,s)\right]} = \frac{e^{-y_{L}}}{s(1 - e^{-y_{L}})}$$

 $t \gg 1$

$$\mathcal{N}(t)\simeq \sqrt{rac{4Dt}{\pi L^2}} \qquad ext{when}$$

Optimization in first-passage resetting

Consider now:

- $\triangleright x(t)$ models the operating point of a system;
- $\triangleright x(t) \ge 0$ and if x(t) = L the system breaks down, incurring a cost C;
- \triangleright control mechanism modelled by a drift v.

And seek to maximize:

$$\mathcal{F} = \lim_{T \to \infty} \frac{1}{T} \left[\frac{1}{L} \int_0^T \langle x(t) \rangle \ dt - C \mathcal{N}(T) \right].$$

Convection diffusion equation for the pdf P(x, t):

$$\partial_t P + v \partial_x P = D \partial_{xx} P + \delta(x) (-D \partial_x P + v P)|_{x=L},$$

subject to the initial and boundary conditions

$$\begin{cases} (D\partial_x P - vP)|_{x=0} = \delta(t), \\ P(L,t) = P(x,0) = 0. \end{cases}$$

It admits a steady-state solution,

$$P(x) \simeq rac{1}{L} imes rac{1 - e^{-2\operatorname{Pe}{(L-x)/L}}}{1 - \operatorname{Pe}^{-1}e^{-\operatorname{Pe}{\operatorname{sinh}}}(\operatorname{Pe}{})}$$

where $Pe \equiv vL/2D$ is the Péclet number.

First-passage resetting in Brownian motion: optimization

From the steady-state solution, one obtains the normalized first moment:

$$\frac{\langle x \rangle}{L} = \frac{1}{L} \int_0^L x P(x) \, \mathrm{d}x = \frac{(2\mathsf{Pe}^2 - 2\mathsf{Pe} + 1) e^{2\mathsf{Pe}} - 1}{2\mathsf{Pe}\left[(2\mathsf{Pe} - 1) e^{2\mathsf{Pe}} + 1\right]} \, .$$

Again with a backward equation, one also obtains the average number of breakdowns:

$$\mathcal{N}(T) \simeq rac{4 \mathrm{Pe}^2}{2 \mathrm{Pe} - 1 + e^{-2 \mathrm{Pe}}} \; rac{T}{L^2/D}$$

Hence:

$$\mathcal{F} \simeq \frac{\left(2 {\mathsf{P}} {\mathsf{e}}^2 - 2 {\mathsf{P}} {\mathsf{e}} + 1\right) \, {\mathsf{e}}^{2 {\mathsf{P}} {\mathsf{e}}} - 1}{2 {\mathsf{P}} {\mathsf{e}} \left[(2 {\mathsf{P}} {\mathsf{e}} - 1) \, {\mathsf{e}}^{2 {\mathsf{P}} {\mathsf{e}}} + 1 \right]} \, - \, \frac{4 {\mathsf{P}} {\mathsf{e}}^2}{2 {\mathsf{P}} {\mathsf{e}} - 1 + {\mathsf{e}}^{-2 {\mathsf{P}} {\mathsf{e}}}} \, \frac{C}{L^2/D} \, ,$$

with $Pe \equiv vL/2D$ the Péclet number.

First-passage resetting in Brownian motion: optimization



Objective function \mathcal{F} in terms of Péclet number $Pe \equiv v L/2D$ for different values of normalized cost $C' \equiv C/(L^2/D)$.

Variations include:

- ▷ delay for "repairs" after breakdown [de Bruyne, R-F, Redner 2020, 2021a]
- ▷ boundary recession [de Bruyne, R-F, Redner 2021a, 2022]
- ▷ higher-dimensional cases [Sherman 1957, de Bruyne, R-F, Redner 2021a]
- ▷ reset at random point [Feller 1953, Sherman 1957, Grigorescu, Kang 2007]
- ▷ multi-particle resetting [de Bruyne, R-F, Redner 2021b]

Multi-particle first-passage resetting

▷ multi-particle resetting: eg two "altruistic" particles



 \triangleright Compare "altruistic" vs "individualistic" systems – eg for N = 2 agents

Use order statistics $+ X_a(t) = \frac{x_1(t) + x_2(t)}{2}$ follows a BM with diff. cst $D_{\parallel} = D/2$



 \triangleright Compare "altruistic" vs "individualistic" systems – eg for N = 16 agents

Use order statistics + $X_a(t) = \frac{x_1(t)+...x_N(t)}{2}$ follows a BM with diff. cst $D_{\parallel} = D/N$



A first-passage problem for the Brownian supremum

A (toy) foraging problem (by P. Krapivsky)



 \triangleright "forager" on a line \rightarrow Brownian walker with position B(t)

 \triangleright one unit of "food" per unit length, no food replenishment

▷ "metabolism": walker stockpiles, needs one unit of food per unit time

▷ survival probability?



▷ "forager" on a line → Brownian walker with position B(t)
▷ one unit of "food" per unit length, no food replenishment
▷ "metabolism": walker needs one unit of food per unit time
▷ food on > 0 side only

One-sided version: a hitting-time problem for the supremum



$$M(s) = \sup_{0 \le \tau \le s} B(\tau)$$

Survival probability is:

Letting

 $P(t) = \operatorname{Prob}(M(s) > s, \forall s \leq t)$

Survival probability
$$P(t) = \operatorname{Prob}\left(M(s) > s, \, \forall s \leq t\right)$$

$$f(t) = -\frac{\mathrm{d}}{\mathrm{d}t} P(t)$$

Probability density function (pdf) of extinction time \parallel

Pdf of first hitting time for M(s) on the diagonal, $\inf_{s>0} \{M(s) - s = 0\}$

Path going extinct at $t \Rightarrow M(t) = t$, but...

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 $M(t) = t \Rightarrow$ path going extinct at t

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because path could have gone extinct before.



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$$f(t) = \underbrace{\operatorname{pdf} (M(t) = t)}_{pdf (M(t) = t)} - \underbrace{g(t)}_{g(t)}$$

paths with M(t) = tand

M(s) = s for some s < t

Path going extinct at $t \Rightarrow M(t) = t$, but...

 $M(t) = t \Rightarrow$ path going extinct at t

because path could have gone extinct before.

$$f(t) = \underbrace{\sqrt{\frac{2}{\pi t}} \exp\left(-\frac{t}{2}\right)}_{paths with M(t)=t} - \underbrace{g(t)}_{g(t)}$$

paths with M(t)=tand M(s)=s for some s < t Given a path with M(t) = t

and M(s) = s for some s < t, define:

▷ hitting time of M(s) = s:

$$\tau_0 = \inf \{r > 0, B(r) = M(s) \text{ i.e. } B(r) = s \}$$

 \triangleright first time level *s* is hit after τ_0 :

 $\delta = \inf \{r > \tau_0, B(r) \ge M(s) \text{ i.e. } B(r) \ge s\}$



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Then

 \triangleright Note: path between τ_0 and δ is a (downward) excursion

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and M(s) = s for some s < t, define:

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 \triangleright first time level *s* is hit after τ_0 :

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Then

- \triangleright Note: path between τ_0 and δ is a (downward) excursion
- $\triangleright\,$ Idea : extract this excursion & use it to hit a new global maximum >t



> Define hitting time of the global maximum,

$$\tau_* = \inf \{r > 0, B(r) = M(t) \text{ i.e. } B(r) = t\}$$

- $\triangleright\,$ extract excursion & bring "forward" (to $\tau_{\rm 0})$ the $[\delta,\tau_*]$ part
- \triangleright insert then the excursion transformed into an (upward) first passage bridge
- \triangleright insert the final, post- τ_* part shifted upward as needed

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- \triangleright insert then the excursion transformed into an (upward) first passage bridge
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- \hookrightarrow obtain a path with global maximum > t



Start with a Brownian path having M(t) > t, and set:

$$\tau_1 = \inf \{s > 0, B(s) = t\}, \quad \tau_* = \inf \{s > 0, B(s) = M(t)\},$$

and
$$\tau_2 = \inf \{s > 0, B(s) = [M(t) + t]/2\}.$$



Note that B(0) - 0 = 0 and $B(\tau_1) - \tau_1 = t - \tau_1 > \tau_2 - \tau_1$, so

 $\exists \tau_0 \in]0, \tau_1[\text{ s.t. } \tau_0 = \inf \{s > 0, B(s) - s = \tau_2 - \tau_1\}.$



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Decompose the Brownian path as follows:

- $\triangleright\,$ take the τ_1 to $\tau_*\,$ part out,
- \triangleright form an excursion of duration $\tau_* \tau_1$ with subpath $[\tau_1, \tau_*]$
- \triangleright insert excursion (downward) at time au_0
- \triangleright append then the $[\tau_0,\tau_1]$ part and the post- τ_* part



 \Leftrightarrow obtain a path with M(t) = t, "dying" (for sure) at time $s = \tau_0 + \tau_2 - \tau_1$.

Recall:

$$f(t) = \sqrt{\frac{2}{\pi t}} \exp\left(-\frac{t}{2}\right) - \underbrace{g(t)}_{\text{paths with } M(t)=t}$$

and

M(s) = s for some s < t

Now:

$$f(t) = \sqrt{\frac{2}{\pi t}} \exp\left(-\frac{t}{2}\right) - \underbrace{g(t)}_{\text{paths with } M(t) \geq t}$$

paths with M(t) > t

That is,

$$f(t) = \sqrt{\frac{2}{\pi t}} \exp\left(-\frac{t}{2}\right) - \int_{t}^{\infty} \sqrt{\frac{2}{\pi t}} \exp\left(-\frac{m^{2}}{2t}\right) dm$$

Finally:

$$f(t) = \sqrt{\frac{2}{\pi t}} \exp\left(-\frac{t}{2}\right) - \operatorname{erfc}\left(\sqrt{\frac{t}{2}}\right)$$

PDF of extinction time in the one-sided case

Finally:

$$f(t) = \sqrt{\frac{2}{\pi t}} \exp\left(-\frac{t}{2}\right) - \operatorname{erfc}\left(\sqrt{\frac{t}{2}}\right)$$

Two other approaches:

- \triangleright look at the reciprocal process of M(s) s
 - \rightarrow this is a spectrally positive Lévy process
- ▷ show that the first passage time of M(t) tis distributed like the sojourn time above 0 of the process B(t) - t

R.A. Doney Hitting probabilities for spectrally positive Lévy processes, Journal of the LMS, 2(3):566-576 (1991) J-P Imhof On the time spent above a level by Brownian motion with negative drift Adv. in Appl. Prob., 18(4):1017-1018 (1986) A first-passage problem for the Brownian range

▷ "forager" on a line → Brownian walker with position B(t)
▷ one unit of "food" per unit length, no food replenishment
▷ "metabolism": walker needs one unit of food per unit time
▷ food on both sides

Letting

$$R(s) = \sup_{0 \le \tau \le s} B(\tau) - \inf_{0 \le \tau \le s} B(\tau)$$

Survival probability is now:

 $P(t) = \operatorname{Prob}(R(s) > s, \forall s \leq t)$

Two-sided version: a hitting-time problem for the range



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Path going extinct at $t \Rightarrow R(t) = t$, but...

 $R(t) = t \Rightarrow$ path going extinct at t

because path could have gone extinct before.

$$f(t) = \underbrace{\operatorname{pdf} (R(t) = t)}_{pdf (R(t) = t)} - \underbrace{g(t)}_{g(t)}$$

paths with R(t) = tand (1)

R(s) = s for some s < t

Path going extinct at $t \Rightarrow R(t) = t$, but...

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paths with R(t)=tW. Feller, Ann. Math. Statist. 22, 427 (1951)

$$f(t) = \underbrace{\frac{8}{\sqrt{2\pi t}} \sum_{k=1}^{\infty} (-1)^{k-1} k^2 e^{-\frac{k^2 t}{2}}}_{k=1} - \underbrace{g(t)}_{k=1}$$
(2)

paths with R(t)=tand

R(s) = s for some s < t

- ongoing work with P. Salminen, P. Vallois & P. Krapivsky

Many thanks for the invitation and for your attention!