# Elliptic Flow Fluctuations with the PHOBOS detector

Burak Alver Massachusetts Institute of Technology

v<sub>2</sub> fluctuations at PHOBOS

# **PHOBOS Collaboration**





Burak Alver, Birger Back, Mark Baker, Maarten Ballintijn, Donald Barton, Russell Betts, Richard Bindel,
Wit Busza (Spokesperson), Zhengwei Chai, Vasundhara Chetluru, Edmundo García, Tomasz Gburek, Kristjan
Gulbrandsen, Clive Halliwell, Joshua Hamblen, Ian Harnarine, Conor Henderson, David Hofman, Richard Hollis,
Roman Holynski, Burt Holzman, Aneta Iordanova, Jay Kane,Piotr Kulinich, Chia Ming Kuo,
Wei Li, Willis Lin, Constantin Loizides, Steven Manly, Alice Mignerey, Gerrit van Nieuwenhuizen,
Rachid Nouicer, Andrzej Olszewski, Robert Pak, Corey Reed, Eric Richardson, Christof Roland,
Gunther Roland, Joe Sagerer, Iouri Sedykh, Chadd Smith, Maciej Stankiewicz, Peter Steinberg,
George Stephans, Andrei Sukhanov, Artur Szostak, Marguerite Belt Tonjes, Adam Trzupek,
Sergei Vaurynovich, Robin Verdier, Gábor Veres, Peter Walters, Edward Wenger, Donald Willhelm,
Frank Wolfs, Barbara Wosiek, Krzysztof Wozniak, Shaun Wyngaardt, Bolek Wyslouch

ARGONNE NATIONAL LABORATORY INSTITUTE OF NUCLEAR PHYSICS PAN, KRAKOW NATIONAL CENTRAL UNIVERSITY, TAIWAN UNIVERSITY OF MARYLAND BROOKHAVEN NATIONAL LABORATORY MASSACHUSETTS INSTITUTE OF TECHNOLOGY UNIVERSITY OF ILLINOIS AT CHICAGO UNIVERSITY OF ROCHESTER

# **Motivation**



**Can we test the Participant Eccentricity Model?** 

# **Expected fluctuations**





Expected  $\sigma_{\text{v2}}$  from fluctuations in  $\epsilon_{\text{part}}$ 



Burak Alver - MIT

# **Measuring v<sub>2</sub> Fluctuations**

- We have considered 3 different methods
  - 2 particle correlations  $\rightarrow \langle v_2^2 \rangle$ 
    - c.f. S. Voloshin nucl-th/0606022
    - $\sigma_{v2}^2 = \langle v_2^2 \rangle \langle v_2^2 \rangle^2$
    - Do systematic errors cancel?
  - 2 particle correlations  $\rightarrow v_2^2$  event by event
    - Mixed event background generation is possible
    - Reduces fit parameters to 1 (no reaction plane)
    - Hard to untangle acceptance effects event by event
  - $-v_2$  event by event
    - This is the method we are pursuing

# **Measuring v<sub>2</sub> Fluctuations - Today's Talk**

- Measuring v<sub>2</sub> event by event
- Ongoing analysis on 200GeV Au-Au
- Today
  - How we are planning to make the measurement
  - Studies on fully simulated MC events
    - Modified Hijing Flow
    - Geant

# **Method Overview - Simplified Example**



Event by Event measurement



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Question: What is the relative abundance of  $v_{2a}$  to  $v_{2b}$  in the sample?

u

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Question: What is the relative abundance of  $v_{2a}$  to  $v_{2b}$  in the sample?

 $g(u)=f_aK_a(u) + f_bK_b(u)$ 

#### **Method Overview**

# In real life v<sub>2</sub> can take a continuum of values

$$g(u) = \int_0^\infty K(u, v_2) f(v_2) dv_2$$

#### Extracted $v_{2true}$ distribution from sample



0.1

u



Ò.

0.05



0.1

0.05 ب

# **Method Overview**

- 3 Tasks
  - Measure u event-by-event g(u)
  - Calculate the kernel K(u,v<sub>2</sub>)
  - Extract dynamical fluctuations f(v<sub>2</sub>)

$$g(u) = \int_0^\infty K(u, v_2) f(v_2) dv_2$$

# **PHOBOS Detector**

- PHOBOS Multiplicity Array

   -5.4<η<5.4 coverage</li>
   -Holes / granularity differences
- Idea: Use all available information in event to read off single *u* value





# Measuring u=v<sub>2obs</sub> Event by Event I

• **Probability Distribution Function (PDF) for hit positions:** 



• Define likelihood of u and  $\phi_0$  for an event:

$$L(u,\phi_0) = \prod_{i=1}^n P(\eta_i,\phi_i|u,\phi_0)$$

# **Measuring u=v<sub>2obs</sub> Event by Event II**

$$L(u,\phi_0) = \prod_{i=1}^n p(\eta_i) [1 + 2u(1 - |\eta_i|/6)\cos(2(\phi_i - \phi_0))]$$

- Maximize likelihood to find "most likely" value of *u*
- Comparing values of u and  $\phi_0$ 
  - In an event,  $p(\eta_i)$  is same for all *u* and  $\phi_0$ .
  - PDF folded by acceptance must be normalized to the same value for different *u* and  $\phi_0$ 's

Acceptance

$$s(u,\phi_0|\eta) = \int (A(\eta,\phi)) \left[1 + 2 u \left(1 - |\eta|/6\right) \cos(2(\phi - \phi_0))\right] d\phi \, d\eta$$

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# **Measuring u=v<sub>2obs</sub> Event by Event III**



Next Step: Construct the Kernel to unfold g(*u*)

$$g(u) = \int_0^\infty K(u, v_2) f(v_2) dv_2$$

# **Calculating the Kernel I**

- Simple: Measure u distribution in bins of v<sub>2</sub>
- 2 small complications
  - Kernel depends on multiplicity: K(u,v<sub>2</sub>,n)
    - *n* = number of hits on the detector
    - Measure u distribution in bins of  $v_2$  and n.
  - Statistics in bins can be combined by fitting smooth functions



# **Calculating the Kernel II**

# • In a single bin of $v_2$ and n

*u* distribution with for fixed v<sub>2</sub> and *n*   $starting 10^2$   $10^2$  $10^2$ 

$$K(u)|_{v_2,n} = u \cdot exp\left(-\frac{u-a^2}{2b^2}\right)$$

$$(a, b) \leftrightarrow (\langle u \rangle, \sigma_u)$$

- Distribution is not Gaussian
- But can be parameterized by  $\langle u \rangle$  and  $\sigma_u$

# **Calculating the Kernel III**

- Measure  $\langle u \rangle$  and  $\sigma_u$  in bins of  $v_2$  and n
- Fit smooth functions



# **Calculating the Kernel IV**

# Multiplicity dependence can be integrated out



$$\underline{g(u)} = \int_0^\infty \frac{K(u, v_2)f(v_2)dv_2}{\sqrt{2}}$$
known
?









Compare expected g(u) for Ansatz with measurement

Minimum  $\chi^2 \rightarrow \langle v_2 \rangle$  and  $\sigma_{v_2}$ 

# **Method Summary**



# Verification

- Ran this analysis on Modified Hijing
  - $-v_2(\eta) = v_2(0) \cdot (1-|\eta|/6)$ 
    - Same as the assumption in our fit
  - $-v_2(0)$  given by a Gaussian distribution in each sample
    - Same as our Ansatz
  - Analysis done in 10 collision vertex bins
    - Final results are averaged
  - 0-40% central events used to construct Kernel
  - 15-20% central events used as sample

# Verification

- Ran this analysis on Modified Hijing
  - The input fluctuations are reconstructed successfully







# **Conclusion / Outlook**

- A new method to measure elliptic flow fluctuations is developed.
- Fluctuations in MC simulations are successfully reconstructed.
- Ready to apply the method to extract dynamical fluctuations in DATA.
  - Important part will be to estimate systematic uncertainties due to the MC/DATA differences
    - dN/dղ(ղ)
    - v<sub>2</sub>(η)
    - Non-flow in data
      - Should show up in reaction plane resolutions

# **Likelihood Fit Normalization**



$$L(u,\phi_0) = \prod_{i=1}^n \frac{1}{s(u,\phi_0|\eta_i)} \left[1 + 2u\left(1 - |\eta_i|/6\right)\cos(2(\phi_i - \phi_0))\right]$$

# **Calculating the Kernel. Functions observed to fit the Kernel**



 $< u > (v_2, n) = \sqrt{(M_1 n^2 + M_2 n + M_3) \cdot v_2^2 + (M_4 * n + M_5)}$ 

$$\sigma_u(v_2, n) = \frac{R_1}{(R_2\sqrt{n+1}) \cdot (1 + \frac{2}{3}e^{(R_3n + R_4)v_2})}$$

