

Testing General Relativity with Interplanetary Spacecraft

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Testing gravitational theories in the solar system

Deflection of light

$$\theta_{gr} = 2(1+\gamma)\frac{M_{sun}}{b} = 4 \times 10^{-6} (1+\gamma)\frac{R_{sun}}{b} \text{ rad}$$
Solar Gravity
Time delay
$$Frequency shift$$

$$+\gamma)M_{sun}\ln\frac{l_0+l_1+l_{01}}{l_0+l_1-l_{01}}$$

$$\frac{\Delta v}{v} = 2\frac{v_1l_0+v_0l_1}{l_0+l_1} \theta_{gr} \cong 4(1+\gamma)\frac{M_{sun}}{b}\frac{db}{dt}$$

 $\approx 8 \times 10^{-10}$ for a grazing beam

 \approx 70 km for a grazing beam

 $\Delta t = (1$



From:

Clifford M. Will, "The Confrontation between General Relativity and Experiment", Living Rev. Relativity, 9, (2006), 3. http://www.livingreviews.org/lrr-2006-3

GR signal and GR signal + residuals (Cassini SCE1)



DSS25 and Cassini







2

0

Spacecraft position wrt sun (y)

6

8

4

-4

10

15

-8

-6

-4

-2

5

0

Days from conjunction

45

40

35

Impact parameter in solar radii 5 0 5 5 00

15

10

5

0

-15

-10

-5

The trajectory of Cassini in the sky during SCE1



SOHO-divx

LASCO images - SOHO

Plasma noise cancellation

Multifrequency radio link

Best accuracies:

 $\Delta f/f = 10^{-14} \text{ at } 10^3 \text{-} 10^4 \text{s}$ (conjunctions) $\rightarrow 1.5 \ 10^{-6} \text{ m/s}$ $\Delta f/f = 310^{-15} \text{ at } 10^3 \text{-} 10^4 \text{s}$ (oppositions) $\rightarrow 4.5 \ 10^{-7} \text{ m/s}$





DSS 25 -Goldstone

Doppler only!





Cancellation of plasma noise with a multifrequency link

$$\Gamma_{XX} = \Gamma_{nd} + \Gamma_{\uparrow} + \frac{1}{\alpha_{XX}^2} \Gamma_{\downarrow}$$

$$\Gamma_{XK} = \Gamma_{nd} + \Gamma_{\uparrow} + \frac{1}{\alpha_{XK}^2} \Gamma_{\downarrow}$$

$$\Gamma_{KK} = \Gamma_{nd} + \frac{1}{\beta^2} \Gamma_{\uparrow} + \frac{1}{\beta^2 \alpha_{KK}^2} \Gamma_{\downarrow}$$

$$\alpha_{XX} = \frac{f_{X_U}}{f_{X_U}} = \frac{880}{749} \qquad \alpha_{XK} = \frac{f_{K_D}}{f_{X_U}} = \frac{3344}{749}$$

$$\alpha_{KK} = \frac{f_{K_{D}}}{f_{K_{U}}} = \frac{14}{15} \qquad \beta = f_{K_{U}} / f_{X_{U}}$$

X/X Doppler/range observable

X/Ka Doppler/range observable

Ka/Ka Doppler/range observable

Three unknown quantities:

- non-dispersive term
- uplink plasma

- $(\begin{array}{c} \Gamma_{nd} \\ (\begin{array}{c} \Gamma \\ \Gamma \\ \end{array}) \\ (\begin{array}{c} \Gamma_{\downarrow}^{\uparrow} \end{array}) \end{array}$
- downlink plasma

[Bertotti, Comoretto, Iess, 1993]

Cancellation of plasma noise (cont.)

$$\Gamma_{nd} \cong \Gamma_{KK} + \frac{1}{13}\Gamma_{XX} + \frac{1}{35}\Gamma_{XK}$$
$$\Gamma_{\downarrow} \cong 0.67\Gamma_{XX} - 0.67\Gamma_{XK}$$
$$\Gamma_{\uparrow} \cong -1.05\Gamma_{KK} + 1.1 \cdot 10^{-3}\Gamma_{XX} + 1.05\Gamma_{XK}$$

Conclusion:

The Ka/Ka link provides the crucial observable and needs the highest accuracy.

Limitations of the plasma cancellation system

- Scattering effects (strong amplitude and phase scintillation, spectral broadening, difficulty to lock the signal at very small solar elongation angles)
- Magnetic corrections to the refractive index ($\propto \omega_p^2 \Omega_c / \omega_0^3$), appreciable only within 3 solar radii
- Separation of the X and Ka radio beam due the radial dependence of the average refractive index



Physical optics effects : phasor representation of the signal



Deflection of radio waves by the solar corona



Ray paths defined by the eikonal eq.

 $(\nabla \xi_{\mathbf{x}}(\mathbf{r}))^2 = n_{\mathbf{x}}^2$ $(\nabla \xi_{\kappa}(\mathbf{r}))^2 = n_{\kappa}^2$

Compare with GR (to first order):

$$n = 1 + \frac{1 + \gamma}{2} \frac{R_g}{r}$$

Wind speed may be estimated by correlating X and Ka band observables, if Δx is known

Plasma noise in the X/X, X/Ka, Ka/Ka links and the calibrated Doppler observable (daily Allan dev. @1000s, Cassini SCE1) Minimum impact parameter: 1.6 R_s (DOY 172)



Power spectrum of relative frequency shift residuals



ACF of Doppler residuals (Cassini DOY 2001-149)



Noise Signatures in 2-way Doppler Link



The Advanced Media Calibration System for tropospheric dry and wet path delay corrections.





The 34m beam waveguide tracking station DSS 25, NASA's Deep Space Network, Goldstone, California



Dynamical model

Solve-for parameters:

- Spacecraft state vector
- Specular and diffuse reflectivity of the 4m high gain antenna
- Acceleration from anisotropic thermal emission from the three RTG

No clue of anomalous acceleration on Cassini







Pseudo X-band frequency residuals (SCE1) with plasma and tropospheric calibrations



Saturn-centered B-plane plot of the Cassini orbital solutions



P.Tortora, L.Iess, J.J. Bordi, J.E. Ekelund, D. Roth, J. Guidance, Control and Dynamics, 27(2), 251 (2004)

Launch on Soyuz 2-1B/Fregat-M (13 April 2012) (1 August 2013 ?)

Solar Electric Propulsion Chemical Propulsion Arrival: 4 April 2017 (but likely later)



MMO MPO CPM SEPM





MORE: Science Goals

- Spherical harmonic coefficients of the gravity field of the planet up to degree and order 25.
- Degree 2 (C_{20} and C_{22}) with 10⁻⁹ accuracy (Signal/Noise Ratio ~ 10⁴)
- Degree 10 with SNR ~ 300
- Degree 20 with SNR ~ 10
- Love number k_2 with SNR ~ 50.
- Obliquity of the planet to an accuracy of 4 arcsec (40 m on surface needs also SIMBIO-SYS high resolution camera)
- Amplitude of physical librations in longitude to 4 arcsec (40 m on surface needs SIMBIO-SYS high resolution camera).
- C_m/C (ratio between mantle and planet moment of inertia) to 0.05 or better
- C/MR^2 to 0.003 or better.

MORE: Science Goals

- Spacecraft position in a Mercury-centric frame to 10 cm 1m (depending on the tracking geometry)
- Planetary figure, including mean radius, polar radius and equatorial radius to 1 part in 10⁷ (by combining MORE and BELA laser altimeter data).
- Geoid surface to 10 cm over spatial scales of 300 km.
- Topography of the planet to the accuracy of the laser altimeter (in combination with BELA).
- Position of Mercury in a solar system barycentric frame to 1 m.
- PN parameter γ , controlling the deflection of light and the time delay of ranging signals to $2.5*10^{-6}$
- PN parameter β , controlling the relativistic advance of Mercury's perihelion, to 5*10⁻⁶ [now 5*10⁻⁴]
- PN parameter η (controlling the gravitational self-energy contribution to the gravitational mass to $2*10^{-5}$ [now $5*10^{-4}$]
- The gravitational oblateness of the Sun (J_2) to $2*10^{-9}$ [now $1*10^{-7}$ indirect]
- The time variation of $G \left(\frac{d(\ln G)}{dt} \right)$ to $2*10^{-13}$ years⁻¹ [now $1*10^{-12}$]

Fighting Noise

- Dynamical noise and non-gravitational accelerations
- Propagation noise (solar corona, interplanetary plasma, troposphere)
 - Spacecraft and ground instrumentation

Dynamical noise must be reduced to a level compatible with the accuracy of range-rate measurements:

$$\sigma_a = \frac{c}{\tau} \sigma_y = 3 \times 10^{-7} \,\mathrm{cm \, s^{-2}}$$
 at $\tau = 1000 \,\mathrm{s}$

Plasma noise cancellation

Multi-frequency radio link (two-way)

Target accuracy:

 $\Delta f/f = 10^{-14} \text{ at } 10^3 \text{--} 10^4 \text{s}$ $\Delta \rho = 10 \text{ cm}$

 $\sigma_y = 10^{-14}$ is equivalent to a one-way range rate of 1.5 micron/s The corresponding one-way displacement in 1000 s is 1.5 mm





X Ka



 \mathbf{X}

Ka





Istituto Nazionale Di Astrofisica







Z–sensitive axis





.

 10^{1}

11111

10⁰



Dynamical noise must be reduced to a level compatible with the accuracy of range-rate measurements:

1111

10⁻⁴

10⁻⁵

1 1 1 1 1 1

10⁻³



1 1 1 1 1

10⁻²

Frequency [Hz]

1111

10⁻¹

MORE OD concepts were tested by detailed numerical simulations at the Univ. of Pisa.



Simulations provide requirements on accelerometer and radio system for all radio science experiments.

Software used is a prototype for the operational MORE data processing.

Noise model controlled via a namelist file with 35 adjustable parameters (23 for Doppler and 12 for ranging)

Simulations for PPN parameters β , γ , α_1 , α_2





Parameter	Present accuracy	MORE
γ	2×10^{-5}	2×10^{-6}
β	$1 imes 10^{-4}$	2×10^{-6}
η	$5 imes 10^{-4}$	8×10^{-6}
J_2^{\odot}	4×10^{-8}	2×10^{-9}
\dot{G}/G	$9 \times 10^{-13} \mathrm{yr}^{-1}$	$3 \times 10^{-13} \mathrm{yr}^{-1}$

Current accuracies of selected PN parameters and values expected from the BepiColombo MORE experiment. Metric theories of gravity with no preferred frame effects are assumed.

Milani et al. Phys. Rev. D, 66, 082001 (2002).