Laser-Enabled Tests of Gravity:

Recent Advances, Technology Demonstrations, and New Ideas

Slava G. Turyshev, Michael Shao, James G. Williams, Dale H. Boggs

Jet Propulsion Laboratory, California Institute of Technology 4800 Oak Grove Drive, Pasadena, CA 91009 USA

Thomas W. Murphy, Jr.

University of California, San Diego, 9500 Gilman Dr., La Jolla, CA 92093USA Kenneth L. Nordtvedt, Jr.

Northwest Analysis, 118 Sourdough Ridge Rd. Bozeman MT 59715 USA

International Workshop on "Advances in Precision Tests and Experimental Gravitation in Space" Galileo Galilei Institute Arcetri, Firenze (Italy), September 25-27, 2006





Madrid, Spain

Navigation Tracking Requirements (2006)



*Based on the current (2006) set of anticipated missions

Tracking Error Source (1σ Accuracy)	Units	current capability	2010 reqt*	2020 reqt*	2030 reqt*
Doppler/random (60s)	µm/s	30	30	30	20
Doppler/systematic (60s)	µm/s	1	3	3	2
Range/random	m	0.3	0.5	0.3	0.1
Range/systematic	m	1.1	2	2	1
Angles	deg	0.01	0.04	0.04	0.04
ΔVLBI	nrad	2.5	2	1	0.5
Troposphere zenith delay	cm	0.8	0.5	0.5	0.3
lonosphere	TECU	5	5	3	2
Earth orientation (real-time)	cm	7	5	3	2
Earth orientation (after update)	cm	5	3	2	0.5
Station locations (geocentric)	cm	3	2	2	1
Quasar coordinates	nrad	1	1	1	0.5
Mars ephemeris	nrad	2	3	2	1

Interplanetary laser ranging is a very natural step to improve the accuracy

LUNAR LASER RANGING SCEINCE



It is all begun 37 year ago...

Laser Ranges between observatories on the Earth and retroreflectors on the Moon started by Apollo in 1969 and continue to the present

McDonald 2.7 m

- 4 reflectors are ranged:
 - Apollo 11, 14 & 15 sites
 - Lunakhod 2 Rover
- LLR conducted primarily from 3 observatories:
 - McDonald (Texas, USA)
 - OCA (Grasse, France)
 - Haleakala (Hawaii, USA)
- New LLR stations:
 - Apache Point, (NM, USA)
 - Matera (Matera, Italy)
 - South Africa, former OCA LLR equipment





Excellent Legacy of the Apollo Program



The Apollo 11 retroreflector initiated a shift from analyzing lunar position angles to ranges. Today LLR is the **only** continuing experiment since the Apollo-Era





French-built retroreflector array



Lunokhod Rover (USSR, 1972)

Beginning of the laser ranging technology. Today, laser ranging has many applications:

 Satellite laser ranging, communication systems, metrology, 3-D scanning, altimetry, etc.





LUNAR LASER RANGING SCEINCE

Historical Accuracy of LLR





- Raw ranges vary by ~1,000s km
- Present range accuracy ~1.5cm

Solution parameters include:

- Dissipation: tidal and solid / fluid core mantle boundary (CMB);
- Dissipation related coefficients for rotation & orientation terms;
- Love numbers k_{2} , h_{2} , l_{2} ;
- Correction to tilt of equator to the ecliptic – approximates influence of CMB flattening;
- Number of relativity parameters.

Historical Accuracy of the LLR Data



Testing General Relativity with LLR





The EEP violation effect in PPN formalism:

$$\frac{\Delta a}{a} = \frac{2(a_1 - a_2)}{(a_1 + a_2)} = \left(\frac{M_G}{M_I}\right)_1 - \left(\frac{M_G}{M_I}\right)_2, \qquad \frac{M_G}{M_I} = 1 + (4\beta - \gamma - 3)\frac{U}{Mc^2}$$
$$\frac{\Delta a}{a} = \eta \cdot \left(\frac{U_e}{M_e c^2} - \frac{U_m}{M_m c^2}\right) = -\eta \cdot 4.45 \times 10^{-10}, \qquad \eta \equiv 4\beta - \gamma - 3.$$

If $\eta = 1$, this would produce a 13 m displacement of lunar orbit. By 2006, range accuracy is ~1.5 cm, the effect was not seen.

Recent LLR results (September 2006):

16,250 normal points through Jan 11, 2006, including 3 days of APOLLO data (2005)

$$\Delta \left(\frac{M_G}{M_I}\right) = (-0.8 \pm 1.3) \times 10^{-13} - \text{corrected for solar radiation pressure}.$$

 $\frac{\Delta a}{a} = (-1.8 \pm 1.9) \times 10^{-13} - \text{Strong Equivalence Principle} \qquad \eta = 4\beta - \gamma - 3 = (4.0 \pm 4.3) \times 10^{-4}$ Using Cassini '03 result $\gamma - 1 = (2.1 \pm 2.3) \times 10^{-5} \Rightarrow \beta - 1 = (1.0 \pm 1.1) \times 10^{-4}$ $\dot{G}_{G} = (6 \pm 7) \times 10^{-13} \text{ yr}^{-1} \qquad \text{Geodetic precession} \qquad K_{gp} = -0.0005 \pm 0.0047$

 $1/r^2$ force law: 10^{-10} times force of gravity;

Gravitomagnetism (frame-dragging): 0.1%

LUNAR LASER RANGING and TESTS OF GENERAL RELATIVITY

• The APOLLO Project & Apparatus:



Apache Point Observatory Lunar Laser-ranging Operation

- Move LLR back to a large-aperture telescope
 - 3.5-meter: more photons!
- Incorporate modern technology
 - Detectors, precision timing, laser
- Re-couple data collection to analysis/science
 - Scientific enthusiasm drives progress

- Uses 3.5-meter telescope at 9200-ft Apache Point, NM
- Excellent atmospheric "seeing": 1as
- 532 nm Nd:YAG, 100 ps, 115 mJ/pulse, 20 Hz laser
- Integrated avalanche photodiode (APD) arrays
 - Multi-photon & daylight/full-moon

The 3.5 meter telescope prior to laser installation. The laser sits to the left of the red ladder attached to the scope.

Laser Mounted on Telescope

JP







First Light: July 24, 2005







First Light: July 24, 2005





Blasting the Moon





First Lunar Returns: October 19, 2005



30 min: 5 consecutive 5 min runs – 2,400 protons; MLRS got as many for 2000-2002. APOLLO can operate in full-moon; no other LLR station can do that.



Error Source	Round-Trip Time Uncertainty, [ps]	One-Way Range Error, [mm]
Retro Array Orientation	100–300	15–45
APD Illumination	60	9
APD Intrinsic	<50	< 7
Laser Pulse Width	45	6.5
Timing Electronics	20	3
GPS-slaved Clock	7	1
Total Random Uncert.	136–314	20–47

Single-photon random error budget

LUNAR LASER RANGING and TESTS OF GENERAL RELATIVITY

Good Start for APOLLO





Residuals computed with new data

APOLLO Recipe for a **mm**-range:

- 7 ps round-trip travel time error
- ~0.5 m lunar reflectors at ±7° tilt → up to 35 mm RMS uncertainty per photon
- 95 ps FWHM laser pulse \rightarrow 6 mm RMS
- Need $\sim 40^2 = 1600$ photons to beat error
- Calculate ~5 ph/pulse return for APOLLO
- "Realistic" 1 photon/pulse → 20 ph/sec → mm statistics on few-minute timescales





Interplanetary laser ranging is the next logical step

OPTICAL TRACKING FOR FUTURE NAVIGATION

*

Pulsed Lidar Space Missions: History



	Mission	Launch	Objective	Performance
	 Apollo 15, 16, 17 	1971-2	Ranging, MoonSuccess	
Γ	– MOLA I	1992	Ranging, Mars	S/C Lost (Contamination)
	- Clementine	1994	Ranging, Moon	Success (BDMO/NASA)
	– LITE	1994	Profiling, Shuttle	Success (Energy Decline by 30%)
	– Balkan	1995	Profiling	Success (Russia)
	– NEAR	1996	Ranging	Success
	– SLA-01	1996	Ranging, Shuttle	Success
	– MOLA II / MGS	1996	Ranging, Altimeter	Success (Bar dropouts)
	– SLA-02	1997	Ranging, Shuttle	Success
	– MPL/DS2	1999	Ranging	S/C Lost
	– VCL	2000	Ranging	Cancelled
	- SPARCLE/EO-2	2001	Profiling, Shuttle	Cancelled
	 Icesat/GLAS 	2003	Ranging + Profiling	Laser 1, 2, 3 Anomalies
	 Messenger/MLA 	2004	Profiling, Mercury	Cost/Schedule Slips [Son of GLAS]
	 Calipso 	2006	Profiling	Launch delayed [Boeing strike]
-	- T2L2/Jason 2	2007	TT, Altimeter, Ranging	Healthy program (CNES)
	– ADM	2007	Wind Demo.	Was 2006 (ESA)
	– LOLA/LRO	2008	Altimeter, Moon	
	– MLCD/MTO	2009	Lasercomm	Cancelled
	 Mars Smart Lander 	2009	Ranging, Mars	
	– BepiColombo	2011	Altimeter, Ranging	Being Decided (ESA)

*Since 1990, NASA, launched & no reported problems, free-flyer: 1/8







Lunch: Nov. 7, 1996. Currently in circular orbits around Mars at 400km altitude and 2 hour orbit period.



- One of the science payload instruments on Mars Global Surveyor (MGS)
 - PI: David E. Smith, GSFC;
 - DPI: Maria T. Zuber, MIT
- Receiver field of view: 0.85 mrad
- Minimum detectable signal at telescope: 0.4fl/pulse at >00% detection probability
 - \sim 0.1fJ/pulse at >90% detection probability.

MOLA-Earthlink Experiment



Seconds of Day



OPTICAL TRACKING FOR FUTURE NAVIGATION

MOLA Earth Scan (2005)



MGS scans about Earth: Farthshine is seen in MOLA receiver ch#2 as red-orangeyellow in plot from 9/21/2005.

Each day's experiment consisted of two back-to-back scans.

Scans were very repeatable.

-16° 00'

- Performed on 3 scheduled dates with spacecraft (9/21, 9/24, 9/28): at ~ 08:00 UTC.
- Each tested lasted ~ 45 min and involved 2 spacecraft scans of Earth.
- Maximum time Earth laser in MOLA FOV per scan line: ~8 sec
- MOLA saw earthshine in channel 2 detector on all 3 dates – very repeatable.



OPTICAL TRACKING FOR FUTURE NAVIGATION

MLA-Earthlink Experiment Results:





- Performed on 3 scheduled dates with spacecraft in May 2005 (5/26, 5/26, 5/31) at ~ 17:00 UTC
- Each test lasted ~ 5 hours and involved spacecraft scan of Earth over 7 x 7 mrad area.
- Maximum time earth laser in MLA FOV: ~ 5 seconds.
- Passive radiometry scan of earth by MESSENGER was performed earlier in the month and verified spacecraft pointing.
- MLA laser pulses were detected at the ground. MLA also detected laser pulses from ground laser.

First successful 2-way lasercomm at interplanetary distances 24 mln km (acc ± 12 cm).



Accurate test of gravitational deflection of light to 1 part in 10⁹

Sizes of the Effects & Needed Accuracy



		Deflection	B=100 m
Effect	Analytical Form	Value (μas)	Value (pm)
First Order	$2(1+\gamma)rac{M}{R}$	1.75×10^6	8.487×10^{8}
Second Order	$([2(1+\gamma)-eta+rac{3}{4}\delta]\pi-2(1+\gamma)^2)rac{M^2}{R^2}$	3.5	1702
Frame-Dragging	$\pm 2(1+\gamma)\frac{J}{R^2}$	± 0.7	± 339
Solar Quadrupole	$2(1+\gamma)J_2rac{M}{R^3}$	0.2	97

LATOR 1994 Proposal:

- Ground-based interferometer [B = 30km]
- Limited capabilities due to atmosphere

 $(M/R)^2$ term ~0.2% accuracy [B =100 m]: 0.02 µas \Rightarrow 0.1 picorad ~10pm

LATOR 2007 (all in space):

- Interferometer on the ISS [B = 100m]
- Technology exists as a result of NASA investments in astrometric interferometry



The key technologies are already available – SIM, TPF, Starlight, KI



JPL Team X study demonstrates feasibility of LATOR as a MIDEX



To utilize the inherent ISS sun-tracking capability, the LATOR optical packages will be located on the outboard truss segments P6 & S6 outwards



Interferometer on the ISS





LASER ASTROMETRIC TEST OF RELATIVITY SIM Technology Components/Systems **Component Technology Subsystem-Level Testbeds** System-Level 1999 4:Oct2002 8: Jul2005 2001 **Metrology Source** Absolute Metrology 4: Kite Testbed (Metrology Truss) 3:Sep2002; 5:Mar2003 **Picometer** 1999 8: Overall system 6:Sep2003; 7:Jun2004

Knowledge Performance via Multi-Facet Fiducials Modeling/Testbed Technology Integration 1:Aug2001 Numbers before 1: Beam Launchers box labels indicate 1998 2000 HQ Tech Gate #'s 3, 5, 6, 7: мам **TOM Testbed** (1 through 8) (distortion of front Testbed (single baseline end optics) **High Speed CCD** Fringe Tracking picometer testbed) Narrow All 8 Completed & Wide Angle Tests Camera 2:Nov2001 Optical **Delay Line** Nanometer Control 1998 Technology Hexapod 1999 **Reaction Wheel** STB-1 (single baseline Isolator 2: STB-3 (three baseline 1998 nanometer testbed) nanometer testbed)







Solar boundary is complex – how to define the limb of the Sun at 0.1 picorad (or ~1.5 cm)?

Optical Receivers Looking Next to the Limb of the Sun

Spectral filtering:

first stage an interference filter, but most of the rejection comes from heterodyne detection, bandwidth set by laser line width ~ 3 khz bandwidth/300Thz (~ 10^{-11} rejection)

Spatial filtering (coronagraph): to avoid the solar surface, as well as light diffracted by the optical aperture. Leaving just the solar corona as background $(-26mag \Rightarrow 4 mag/arcsec^2, ~10^{-6})$

Possible rejection 10^{-17} , only need $10^{-10} \sim 10^{-11}$ rejection to be photon limited

Fiber-Coupled Tracking Interferometer



- Full aperture ~20cm narrow band-pass filter; corner cube [baseline metrology];
- Steering flat; off-axis telescope w/ no central obscuration [for metrology];
- Coronagraph; ½ plane focal plane occulter; Lyot stop;
- Fibers for each target (1 on S/C and 2 on the ISS).







Eddington Experiment of the 21st Century













Optical vs. Microwave:

 Solar plasma effects decrease as λ²: from 10cm (3GHz) to 1 µm 300 THz is a 10¹⁰ reduction in solar plasma optical path fluctuations

Orbit Determination (OD):

- No need for drag-free environment for LATOR spacecraft
- Redundant optical truss alternative to ultra-precise OD

A Low Cost Experiment:

- Optical apertures ~15-25 cm sufficient; high SNR ~1700
- Options exist for <u>NO</u> motorized moving parts
- Many technologies exist: laser components and spacecraft
- Possibilities for further improvements: clocks, accelerometers, etc.

Toward Centennial of General Relativity (2015):

1919: Light deflection during solar eclipse: $|1 - \gamma| \le 10^{-1}$ 1980: Viking – Shapiro Time Delay: $|1 - \gamma| \le 2 \times 10^{-3}$ 2003: Cassini – Doppler [d(Time Delay)/dt]: $|1 - \gamma| \le 2.3 \times 10^{-5}$ 2016: LATOR – Astrometric Interferometry: $|1 - \gamma| \Rightarrow 10^{-8} - 10^{-9}$





Technology is available to conduct tests in immediate solar proximity

TESTING RELATIVISTIC GRAVITY IN SPACE

35 Years of Relativistic Gravity Tests



Techniques for Gravity Tests:

Radar Ranging:

- Planets: Mercury, Venus, Mars
- s/c: Mariners, Vikings, Cassini, Mars Global Surv., Mars Orbiter
- VLBI, GPS, etc.

Laser:

LLR, SLR, etc.

Designated Gravity Missions:

- LLR (1969 on-going!!)
- GP-A, '76; LAGEOS, '76,'92; GP-B, '04; LISA, 2014

New Engineering Discipline – Applied General Relativity:

- Daily life: GPS, geodesy, time transfer;
- Precision measurements: deep-space navigation & astrometry (SIM, GAIA,....).



A factor of 100 in 35 years is impressive, but is not enough for the near future!

TESTING RELATIVISTIC GRAVITY IN SPACE

Cassini 2003: Where Do We Go From Here?

Cassini Conjunction Experiment 2002:

- Spacecraft—Earth separation > 1 billion km
- Doppler/Range: X~7.14GHz & Ka~34.1GHz
- Result: $\gamma = 1 + (2.1 \pm 2.3) \times 10^{-5}$

Possible with Existing Technologies?!

- VLBI [current γ = 3 ×10⁻⁴]: in 5 years ~5 ×10⁻⁵:
 - # of observations (1.6M to 16M \rightarrow factor of 3)
- LLR [current η = 4 ×10⁻⁴]: in 5 years ~3 ×10⁻⁵:
 - mm accuracies [APOLLO] & modeling efforts
- μ -wave ranging to a lander on Mars $\sim 6 \times 10^{-6}$
- tracking of BepiColombo s/c at Mercury $\sim 2 \times 10^{-6}$
- Optical astrometry [current $\gamma = 3 \times 10^{-3}$]:

SIM & GAIA ~1 ×10⁻⁶ (2015/16?) We need a dedicated mission to explore accuracies better then 10⁻⁶ for both **PPN** parameters γ (and β). Optical and atom technologies show great promise.







MLA-Earthlink Experiment at 1.2 m telescope













Team from GSFC:

X. Sun, G. Neumann, J. Cavanaugh, J. McGarry, T. Zagwodzki, J. Degnan, + many others

Experiment Objectives:

In-flight calibration of instrument – determine instrument pointing relative to spacecraft and laser boresight, verify laser characteristics, verify ranging system performance.

Laser ground system characteristics:

- Laser PRF: 240 Hz Wavelength: 1064 nm
- Energy per pulse: 15 mJ Laser divergence: 55 urad
- Receiver FOV: ~260 urad
- Event time recording: 50 psec shot-to-shot, accurate to UTC to ~100 nsec
- Telescope pointing: 1 arcsec open-loop accuracy, several arcsec jitter during daylight.
- Detector: spare MOLA detector
- Laser: HOMER (B. Coyle Laser Risk Reduction Program developmental)

LASER ASTROMETRIC TEST OF RELATIVITY

Focal Plane Mapping





Summary of design parameters for the LATOR optical receiver system



The LATOR 200mm receiver optical system is located one each of two separate spacecraft to receive optical communication signals form a transmitter on the ISS.

Summary of Recent Transponder Experiments







- Key instrument parameters for recent deep space transponder experiments at 1064 nm
- Note, these were experiments of opportunity and not design
- At the same time, the accuracy of MLA range determination was 12 cm at the distance of 24 mln km from the Earth (Sun et al., 2005, Smith et al., 2005)

Example Data From a 2005 Run





Randomly-timed background photons (bright moon)