Gravitational Memory in Numerical Relativity

- Computing Memory Effects,
- Correcting Waveforms,
- And the importance of BMS Frames

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Conference on Gravitational Scattering, Inspiral and Radiation (virtual) Galileo Galilei Institute, May 6, 2021





# What we are currently seeing...

### GW150914



# What we are currently seeing...

### GW150914



# What we should be seeing...



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# What is gravitational memory?

#### Early Work:

- Zel'dovich and Polnarev (1974).
- Braginsky and Thorne (1987).
  - Christodoulou (1991).
  - Thorne (1992).

#### **Ordinary (linear) Memory:**

Massive objects traveling to asymptotic infinity as  $t \to \infty$ 

$$\Delta h_{ij} = \Delta \sum_{A=1}^{N} \frac{4M_A}{r\sqrt{1 - v_A^2}} \left(\frac{v_A^i v_A^j}{1 - v_A \cos(\theta_A)}\right)^{11}.$$

mm

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#### Null (non-linear) Memory:

Null radiation traveling to asymptotic infinity as  $r, t \rightarrow \infty$  at fixed  $u \equiv t - r$ 

$$\Delta h_{ij} = \frac{4}{r} \int \frac{dE}{d\Omega'} \left( \frac{\xi^{i'} \xi^{j'}}{1 - \cos\left(\theta'\right)} \right)^{\text{TT}} d\Omega$$

where  $\xi'$  is a unit vector from the source to  $d\Omega'$ .

## The BMS Group

BMS Group = Lorentz Group  $\rtimes$  supertranslations



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Extended BMS Group =  $LCKV(S^2) \rtimes$  supertranslations Generalized BMS Group =  $Diff(S^2) \rtimes$  supertranslations



## The BMS Balance Laws

#### **Bondi-Sachs Metric:**

$$ds^{2} = -\left(1 - \frac{2m}{r} + \mathcal{O}\left(\frac{1}{r^{2}}\right)\right) du^{2} - 2\left(1 + \mathcal{O}\left(\frac{1}{r^{2}}\right)\right) dudr$$
$$+ r^{2}\left(q_{AB} + \frac{1}{r}C_{AB} + \mathcal{O}\left(\frac{1}{r^{2}}\right)\right) \left(d\theta^{A} - \mathcal{U}^{A}du\right) \left(d\theta^{B} - \mathcal{U}^{B}du\right)$$

where

$$\mathcal{U}^{A} = -\frac{1}{2r^{2}}D_{B}C^{AB} + \frac{1}{r^{3}}\left[-\frac{2}{3}N^{A} + \frac{1}{16}D^{A}\left(C_{BC}C^{BC}\right) + \frac{1}{2}C^{AB}D^{C}C_{BC}\right] + \mathcal{O}\left(\frac{1}{r^{4}}\right)$$

# The BMS Balance Laws

#### **Bondi-Sachs Metric:**



$$\operatorname{Re}\left[h\right]\left(u,\theta,\phi\right) = \begin{pmatrix} \operatorname{Bondi} \ \operatorname{Mass} \ \operatorname{Charge} \\ + \\ \operatorname{Energy} \ \operatorname{Flux} \end{pmatrix}$$

$$\operatorname{Im} \left[h\right] \left(u, \theta, \phi\right) = \frac{d}{du} \begin{pmatrix} \operatorname{Angular Momentum Charge} \\ + \\ \operatorname{Angular Momentum Flux} \end{pmatrix}$$

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# The BMS Balance Laws (for memory)

$$\Delta \operatorname{Im} \left[h\right] \left(\theta, \phi\right) = \Delta \frac{d}{du} \begin{pmatrix} \operatorname{Angular} & \operatorname{Momentum} & \operatorname{Charge} \\ + \\ \operatorname{Angular} & \operatorname{Momentum} & \operatorname{Flux} \end{pmatrix} \rightarrow \begin{pmatrix} \operatorname{Ordinary} \\ \operatorname{Magnetic} & \operatorname{Memory} \\ \\ \operatorname{Magnetic} & \operatorname{Memory} \end{pmatrix}$$

## What we know about memory

Gravitational memory = the relative displacement of (initially comoving) observers induced by the passage of gravitational radiation

$$\begin{split} \Delta \xi^{\alpha}(u_1, u_0) &= \Delta K^{\alpha}{}_{\beta}(u_1, u_0) \, \xi^{\beta}(u_0) \\ &+ (u_1 - u_0) \, \Delta H^{\alpha}{}_{\beta} \, \dot{\xi}^{\beta}(u_0) + \cdots \end{split}$$

 $\Delta K^{\alpha}{}_{\beta} \rightarrow \text{usual displacement memory}$  $superton \Delta H^{\alpha}{}_{\beta} \rightarrow \text{sub-leading displacement memory}$ 

- spin memory (magnetic)
- center-of-mass memory (electric)

supertranslations

super Lorentz transformations

## Charge-Flux breakdown of the strain

 $h = \left(J_m + J_{\mathscr{C}}\right) + \left(J_{\hat{N}} + J_{\mathscr{J}}\right) \quad \text{[from the BMS balance laws]}$  where











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# Waveform Extraction (extrapolation)

- Obtain metric data on finite-radius world tubes Γ from a BBH evolution
- 2. Interpolate between points on the various world tubes
- 3. Extrapolate to  $r \to \infty$



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#### **Never solve Einstein's equations!**

# Cauchy-characteristic Extraction (CCE)

- Obtain metric data on a finite-radius world tube Γ from a BBH evolution
- 2. Choose initial data for the null hyper surface  $\Sigma_u$
- 3. Evolve  $\Sigma_u$  forward in time
- 4. Get better waveforms!(and Weyl scalars!)



### Dominant Displacement Memory Mode



### Dominant sub-leading Displacement Memory Mode



### Dominant Displacement Memory Mode



# Correcting the Extrapolated Waveforms

$$J_{m} \equiv \frac{1}{2}\bar{\partial}^{2}\mathfrak{D}^{-1}m \longrightarrow Mass Charge$$

$$(J_{\mathcal{B}}) \equiv \frac{1}{2}\bar{\partial}^{2}\mathfrak{D}^{-1}\left[\frac{1}{4}\int_{-\infty}^{u}|\dot{h}|^{2}du\right] \longrightarrow Energy Flux$$

$$J_{\hat{N}} \equiv \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\bar{\partial}\left(\partial_{u}\hat{N}\right)\right] \longrightarrow Angular Momentum Charge$$

$$(J_{\mathcal{J}}) \equiv \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\dot{h}-3\dot{h}\bar{\partial}\bar{h}+\dot{h}\bar{\partial}h-\bar{h}\bar{\partial}\dot{h}\right)\right] \rightarrow Angular Momentum Flux$$

$$u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\dot{h}-3\dot{h}\bar{\partial}\bar{h}+\dot{h}\bar{\partial}h-\bar{h}\bar{\partial}\dot{h}\right)\right] \rightarrow u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\bar{h}-3\dot{h}\bar{\partial}\bar{h}+\dot{h}\bar{\partial}h-\bar{h}\bar{\partial}\dot{h}\right)\right] = u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\bar{h}-3\dot{h}\bar{\partial}\bar{h}+\dot{h}\bar{\partial}h-\bar{h}\bar{\partial}\dot{h}\right)\right] = u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\bar{h}-3\dot{h}\bar{\partial}\bar{h}+\dot{h}\bar{\partial}h-\bar{h}\bar{\partial}\bar{h}\right)\right] = u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\bar{h}-3\dot{h}\bar{\partial}\bar{h}+\dot{h}\bar{\partial}\bar{h}-\dot{h}\bar{\partial}\bar{h}\right] = u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{\partial}\bar{h}-3\dot{h}\bar{h}-\dot{h}\bar{h}\bar{h}\right] = u_{\mathcal{J}} = \frac{1}{2}i\bar{\partial}^{2}\mathfrak{D}^{-1}D^{-2}\mathrm{Im}\left[\frac{1}{8}\partial\left(3h\bar{h}-3h\bar{h}-3\dot{h}\bar{h}-\dot{h}\bar{h}\bar{h}\right] = u_{\mathcal{J}} = u_$$

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Extrapolation missing the flux terms?
• Just compute these and add them on!

### Correcting Waveforms without Memory



### Correcting Waveforms without Memory



 $h = (J_m + J_{\mathscr{C}}) + (J_{\hat{N}} + J_{\mathscr{J}})$  can also serve as a consistency check!

Waveforms should satisfy the constraint

$$h - J = 0$$
, where  $J \equiv (J_m + J_{\mathscr{C}}) + (J_{\hat{N}} + J_{\mathscr{J}})$ 

## Violation of BMS Balance Laws by NR Waveforms



## The Importance of BMS Frames



### What is a BMS Frame?

- LIGO assumes their waveforms are in the center-of-mass frame
- So, map waveforms to the center-of-mass frame using the Poincaré center-of-mass charge:

$$\vec{G} \equiv \frac{1}{\gamma M_B} \frac{1}{4\pi} \int_{S^2} \operatorname{Re} \left[ \left( \bar{\eth} \vec{r} \right) \left( \hat{N} + u \eth m \right) \right] \, d\Omega$$

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#### What about the supertranslation freedom?

## Fixing the Supertranslation Freedom

Fix the supertranslation freedom with a supertranslation charge

• Extend the Bondi four-momentum via the Moreschi supermomentum:  $\Psi^{M} \equiv \Psi_{2} + \sigma \dot{\bar{\sigma}} + \delta^{2} \bar{\sigma}$ 

When this function only has a temporal component, call the BMS frame the "nice section" or the "super rest frame"

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Note,  $\Psi^{M}$  can never be made exactly zero:

$$\Delta \Psi^{\mathbf{M}} \equiv \int_{u_1}^{u_2} \dot{\Psi}^{\mathbf{M}}(u) \, du = \int_{u_1}^{u_2} \left[ \left( \dot{\Psi}_2 + \left[ \sigma \ddot{\sigma} + \delta^2 \dot{\sigma} \right] \right) + |\dot{\sigma}|^2 \right] du = \int_{u_1}^{u_2} |\dot{\sigma}|^2 \, du$$

Vanishes due to the Bianchi identities

## Choices for the super rest frame

- 1. Mapping to the super rest frame using  $\mathcal{I}^-$  data
  - Equivalent to mapping to the "PN BMS frame"
    - i.e., what PN waveforms are in
  - What LIGO and other detectors expect

- 2. Mapping to the super rest frame using  $\mathcal{I}^+$  data
  - Essential for performing quasinormal mode (QNM) analyses

## Benefits of mapping $\mathscr{I}^-$ to the super rest frame



## Combining NR and PN Waveforms



## Benefits of mapping $\mathscr{I}^+$ to the super rest frame



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## Example Memory Values



## Detectability of Gravitational Memory

It won't be easy!

- Can we even detect memory with an interferometer?
- LIGO SNRs for an idealized GW150914 event:
  - Displacement:  $\sim 2$
  - sub-leading:  $\sim 0.05$
- Will rely on "stacking" events
  - Need to break a memory sign degeneracy
  - Need ~  $\mathcal{O}(2000)$  events



### Summary

- Can now produce waveforms with memory
- Waveforms without memory can be corrected
- Waveform accuracy can be tested using the BMS balance laws
- Fixing the BMS frame (via the super rest frame) is critical for modeling and analysis
- Detectability estimates improve with NR waveforms

<u>Phys. Rev. D 102, 104007 (2020)</u>, (arXiv: 2007.11562), K. Mitman, *et al.* 

<u>Phys. Rev. D 103, 024031 (2021)</u>, (arXiv: 2011.01309), K. Mitman, *et al*.

"Fixing the BMS Frame of Numerical Relativity Waveforms" (on arXiv later this week), K. Mitman, *et al.*