Is Schwinger-Keldysh Hydrodynamics Compatible with Thermodynamic Equilibrium?



[250x.xxxx] AJ, Kovtun [2011.03691] AJ, Kovtun, Ritz, Shukla

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Foundations and Applications of Relativistic Hydrodynamics May 05, 2025 • GGI Florence





Stochastic Is Schwinger-Keldysh Hydrodynamics Compatible with Thermodynamic Equilibrium?



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The big picture

► Effective field theory (EFT) is a powerful tool to construct low-energy effective models for complex many-body systems, without the detailed knowledge of their microscopic constituents.

► The conventional EFT framework is only suited to systems at zero temperature or systems in thermal equilibrium (statistical field theory).

Hydrodynamics provides a universal framework to describe low-energy effective dynamics of complex many-body systems operating close to thermal equilibrium.

Classical hydrodynamics is "like" an EFT. It involves effective fields for local fluid velocity, temperature, density, etc, whose dynamics is dictated by universal symmetry principles.

However, it is *not* based on an effective action principle.

This has changed recently!





The big picture

Classical hydrodynamics has limited applicability due to the presence of stochastic thermal fluctuations.

Classical hydrodynamics includes dissipation but not fluctuations, which are neccesiated by the fluctuation-dissipation theorem (FDT).

Schwinger-Keldysh (SK) hydrodynamics is an EFT extension of classical hydrodynamics, which systematically incorporates the effects of stochastic thermal fluctuations.



[Kovtun, Moore, Romatschke 2014] [Harder, Kovtun, Ritz 2015] [Crossley, Glorioso, Liu 2015] [Haehl, Loganayagam, Rangamani 2015] [Jensen, Pinzani-Fokeeva, Yarom 2017]



The hydrodynamic landscape

Hydrodynamics

- Near-equilibrium many-body dynamics
- Based on universal conservation laws
- **×** Includes dissipation but not fluctuations
- **✗** Incompatible with FDT

Statistical Field Theory

- Governs equilibrium configurations
- Equilibrium effective action (free energy)
- Includes (equilibrium) fluctuations
- **×** Cannot be used to obtain dynamics

Stochastic Hydrodynamics

- Includes fluctuations
- ▲ Might violate FDT at loop levels
- **×** Does not include non-linear stochastic noise
- ✗ No effective action principle

Schwinger-Keldysh Hydrodynamics

- ✓ Effection principle for (stochastic) hydrodynamics
- ✓ Includes general stochastic noise
- ✓ Features fully non-linear and loop-level FDT \rightarrow KMS symmetry
- Symmetry based understanding of the second law
- ▲ Fairly new and unexplored!





Outline

- >Hydrostatic compatibility
- Schwinger-Keldysh hydrodynamics

- Hydrostatic compatibility at one-loop
- ► BRST ghosts
- ► Lessons and outlook



Hydrodynamics 101

> Consider hydrodynamics of a conserved scalar variable ψ , with conservation equation

 $\partial_t \boldsymbol{\psi} + \nabla \cdot \mathbf{J} = 0$

Given $\mathbf{J} = \mathbf{J}(\psi)$, this equation governs the classical evolution of ψ . The constitutive relations are given as

$$\mathbf{J} = -D(\psi) \nabla \psi + \sigma(\psi) \mathbf{E} + \mathcal{O}(\nabla \psi) \mathbf{I} + \mathcal{O}(\nabla \psi) \mathbf{I} + \mathbf{I} +$$

► The diffusion and conductivity are related via the chemical potential $\mu(\psi) = \delta F[\psi]/\delta \psi$,

$$D(\psi) = \mu'(\psi) \, \sigma(\psi)$$

Arises from the local second law of thermodynamics, together with $\sigma \geq 0$.



 $\mathbf{E} = \nabla h$ is applied electric field

$$\Rightarrow \quad \mathbf{J} = -\sigma(\psi) \left(\nabla \mu(\psi) - \mathbf{E} \right) + \mathcal{O}(\nabla^2)$$

 $\mathbf{E}(t, \mathbf{x})$

eld

Hydrostatic compatibility

> The second law equality constraints, such as the diffusion-conductivity constraint, ensure the hydrostatic compatibility of classical hydrodynamics:

> In the presence of time-independent background sources, hydrodynamic equations must admit a time-independent equilibrium solution, governed by an equilibrium generating functional.

$$\mathscr{Z}_{eqb}[h] = \int_{eqb} \mathscr{D}\psi \exp\left(-F[\psi] + \int_{\mathbf{X}} h\psi\right)$$

► Classically, the generating functional is dominated by the saddle point $\mu(\psi_{eqb}) = h$.

$$\partial_t \psi_{\text{eqb}} + \nabla \cdot \mathbf{J}_{\text{eqb}} = -\nabla \cdot \left(D(\psi_{\text{eqb}}) \nabla \psi_{\text{eqb}} - \sigma(\psi_{\text{eqb}}) \mathbf{E} \right) + \mathcal{O}(\nabla^3)$$
$$= -\nabla \cdot \left(\left(\frac{D(\psi_{\text{eqb}})}{\mu'(\psi_{\text{eqb}})} - \sigma(\psi_{\text{eqb}}) \right) \nabla h \right) + \mathcal{O}(\nabla^3) = 0$$

We will take $\beta = 1/(k_B T) = 1$.

[Banerjee et al. 2012] [Jensen et al. 2012]

This solves the hydrodynamic equation, provided that the second law equality constraints are obeyed



Model A and Model B

► We will consider a slight generalisation of our scalar hydrodynamic model [Hohenberg, Halperin 1977]

 $\partial_t \psi + \Gamma$

$$\Gamma = \Gamma(\psi)$$

$$\Gamma = -\nabla \cdot \left(\sigma(\psi) \nabla \circ \right)$$

Technically, only Model B is hydrodynamic.

► For concreteness, we use

$$F[\psi] = \frac{1}{2} \int_{\mathbf{x}} \left(\gamma (\nabla \psi)^2 + a_2 \psi^2 + \frac{1}{3} a_3 \psi^3 + \frac{1}{12} a_4 \psi^4 \right) \qquad \Gamma(\psi) = \Gamma_0 + \Gamma_1 \psi + \frac{1}{2} \Gamma_2 \psi^2 \qquad \text{(Model A)}$$
$$\mu(\psi) = \left(a_2 - \gamma \nabla^2 \right) \psi + \frac{1}{2} a_3 \psi^2 + \frac{1}{6} a_4 \psi^3 \qquad \sigma(\psi) = \sigma_0 + \sigma_1 \psi + \frac{1}{2} \sigma_2 \psi^2 \qquad \text{(Model B)}$$

$$= \frac{1}{2} \int_{\mathbf{x}} \left(\gamma (\nabla \psi)^{2} + a_{2} \psi^{2} + \frac{1}{3} a_{3} \psi^{3} + \frac{1}{12} a_{4} \psi^{4} \right) \qquad \Gamma(\psi) = \Gamma_{0} + \Gamma_{1} \psi + \frac{1}{2} \Gamma_{2} \psi^{2} \qquad \text{(Model A)}$$
$$\mu(\psi) = \left(a_{2} - \gamma \nabla^{2} \right) \psi + \frac{1}{2} a_{3} \psi^{2} + \frac{1}{6} a_{4} \psi^{3} \qquad \sigma(\psi) = \sigma_{0} + \sigma_{1} \psi + \frac{1}{2} \sigma_{2} \psi^{2} \qquad \text{(Model B)}$$

$$\Gamma\left(\mu(\psi) - h\right) = 0$$

if ψ is not conserved (Model A) if ψ is conserved (Model B)



Hydrostatic compatibility of correlation functions

Hydrodynamics can be used to compute *classical* retarded correlation functions

$$G^{\text{ret,cl}} \equiv \frac{\delta}{\delta h} \psi_{\text{onshell}}[h]$$

$$G^{\text{ret,cl}}(\omega, \mathbf{k})_{(A)} = \frac{\Gamma_0}{(a_2 + \gamma \, \mathbf{k}^2) \,\Gamma_0 - i\omega} \qquad G^{\text{ret,cl}}(\omega, \mathbf{k})_{(B)} = \frac{\sigma_0 \, \mathbf{k}^2}{(a_2 + \gamma \, \mathbf{k}^2) \,\sigma_0 \, \mathbf{k}^2 - i\omega} \qquad \Gamma_{(A)} = \Gamma_0 + \dots$$

► The equilibrium correlation functions are governed by the generating functional

Hydrostatic compatibility implies

 $G^{\text{ret,cl}}$

Similar compatibility conditions exist for higher-point correlation functions.

[Kadanoff, Martin 1963]

$$\partial_t \psi + \Gamma \Big(\mu - h \Big) = 0$$

$$^{l}(\omega = 0,\mathbf{k}) = G^{eqb,cl}(\mathbf{k})$$



Stochastic hydrostatic compatibility

► Hydrostatic compatibility must remain intact in the presence of interactions

$$G^{\text{ret,cl}}(\omega = 0, \mathbf{k}) = G^{\text{eqb,cl}}(\mathbf{k})$$

 \succ $G^{eqb}(\mathbf{k})$ can be obtained using the equilibrium generating functional. One-loop corrections:



> To compute $G^{\text{ret}}(\mathbf{k})$, we need the framework of Schwinger-Keldysh (stochastic) hydrodynamics.

Is Schwinger-Keldysh hydrodynamics compatible with hydrostatics?

$$G^{\text{ret}}(\omega = 0, \mathbf{k}) \stackrel{?}{=} G^{\text{eqb}}(\mathbf{k})$$

$$F[\psi] = \frac{1}{2} \int_{\mathbf{X}} \left(\gamma \, (\nabla \psi)^2 + a_2 \, \psi^2 + \frac{1}{3} \, a_3 \, \psi^3 + \frac{1}{12} \, \phi^3 +$$





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Outline

- Hydrostatic compatibility
- Schwinger-Keldysh hydrodynamics

- Hydrostatic compatibility at one-loop
- ► BRST ghosts
- ► Lessons and outlook





Stochastic fluctuations

Fluctuation-dissipation theorem relates retarded correlation functions to symmetric correlation functions

 $\langle \psi^2 \rangle$

*We will take $\beta = 1/(k_B T) = 1$.

$$G^{\text{sym}}(\omega, \mathbf{k}) = \frac{2}{\omega} \operatorname{Im} G^{\text{ret}}(\omega, \mathbf{k})$$
$$(\psi) = \psi(t) \sim e^{-\#t}$$

Symmetric functions compute stochastic fluctuations of a variable, which are absent in classical hydrodynamics.

Fluctuations backreact on hydrodynamics via interactions and induce stochastic-loop corrections in retarded correlation functions.

Schwinger-Keldysh (SK) hydrodynamics provides a systematic symmetry-based EFT framework that incorporates the effects of stochastic thermal fluctuations.



MSR path integral

► Stochastic hydrodynamics with Gaussian noise:

 $\langle \theta(t, \mathbf{x}) \rangle = 0$

$$\langle \theta(t, \mathbf{x}) \, \theta(t', \mathbf{x}') \rangle = 2 \, \delta(t - t', \mathbf{x} - \mathbf{x}')$$

► Martin-Siggia-Rose (MSR) path integral [Martin, Siggia, Rose 1973]

$$G^{\text{ret}} = \frac{\delta}{\delta h_r} \frac{-i\delta}{\delta h_a} \ln \mathscr{Z}[h_r, h_a] = \frac{\delta}{\delta h_r} \langle \psi_r \rangle$$

$$G^{\text{sym}} = \frac{-i\delta}{\delta h_a} \frac{-i\delta}{\delta h_a} \ln \mathscr{Z}[h_r, h_a] = \langle \psi_r^2 \rangle - \langle \psi_r \rangle^2$$

$$\frac{\partial_t \psi_r + \Gamma\left(\mu(\psi_r) - h_r\right) + f(\psi_r) \theta}{E} = 0$$

$$f^2 = \Gamma \text{ due to FDT}$$

$$\langle \dots \rangle = \int \mathcal{D}\theta (\dots)_{\text{onshell}} \exp\left(-\frac{1}{4}\int_x \theta^2\right) \qquad \psi \equiv \langle \psi_r \rangle$$

 $h_a \psi_r$



MSR path integral

Stochastic hydrodynamics with Gaussian noise:

 $\langle \theta(t, \mathbf{x}) \rangle = 0$

$$\langle \theta(t, \mathbf{x}) \, \theta(t', \mathbf{x}') \rangle = 2 \, \delta(t - t', \mathbf{x} - \mathbf{x}')$$

► Martin-Siggia-Rose (MSR) path integral [Martin, Siggia, Rose 1973]

$$\mathcal{Z}[h_r, h_a] = \int \mathcal{D}\theta \, \mathcal{D}\psi_r \, \delta[E + f\theta] \, \exp\left(i\int_x \frac{i}{4}\theta^2 + h_a\psi_r\right) = \int \mathcal{D}\theta \, \mathcal{D}\psi_r \, \mathcal{D}\phi_a \exp\left(i\int_x \frac{i}{4}\theta^2 - \phi_a\left(E + f\theta\right) + h_a\psi_r\right)$$

$$G^{\text{ret}} = \frac{\delta}{\delta h_r} \frac{-i\delta}{\delta h_a} \ln \mathcal{Z}[h_r, h_a] = \frac{\delta}{\delta h_r} \langle\psi_r\rangle = \int \mathcal{D}\psi_r \, \mathcal{D}\phi_a \exp\left(i\int_x i\Gamma \phi_a^2 - \phi_a E + h_a\psi_r\right)$$

$$G^{\text{sym}} = \frac{-i\delta}{-i\delta} \frac{-i\delta}{\ln \mathcal{Z}} \ln \mathcal{Z}[h_r, h_a] = \langle\psi_r\rangle_{-1}^2$$

$$G^{\text{ret}} = \frac{\delta}{\delta h_r} \frac{-i\delta}{\delta h_a} \ln \mathscr{Z}[h_r, h_a] = \frac{\delta}{\delta h_r} \langle \psi_r \rangle$$

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$$\partial_t \psi_r + \Gamma \left(\mu(\psi_r) - h_r \right) + f(\psi_r) \theta = 0$$

$$f^2 = \Gamma \text{ due to } F$$

$$\langle \dots \rangle = \int \mathcal{D} \theta \left(\dots \right)_{\text{onshell}} \exp \left(-\frac{1}{4} \int_x^x \theta^2 \right) \qquad \psi = h$$









Schwinger-Keldysh generating functional

► Schwinger-Keldysh generating functional $\mathscr{Z}[h_r, h_a]$

$$G^{\text{ret}} = \frac{\delta}{\delta h_r} \frac{-i\delta}{\delta h_a} \ln \mathcal{Z}[h_r, h_a] \qquad G^{\text{sym}} = \frac{-i\delta}{\delta h_a} \frac{-i\delta}{\delta h_a}$$

Microscopic unitarity constraints:

$$\mathscr{Z}\Big|_{h_a \to 0} = 1$$
 $\mathscr{Z}\Big|_{h_a \to -h_a} = \mathscr{Z}^*$ $\operatorname{Re} \mathscr{Z} \leq 0$

Kubo-Martin-Schwinger (KMS) symmetry:

$$K h_r(t) = h_r(-t)$$
$$K h_a(t) = \left(h_a + i\partial_t h_r\right)(-t)$$



Schwinger-Keldysh effective field theory

Schwinger-Keldysh effective field theory (SK-EFT)

$$\mathscr{Z}[h_r, h_a] = \int \mathscr{D}\Psi_r \mathscr{D}\Psi_a \exp\left(iS[\Psi_r, \Psi_r]\right)$$

➤ The SK-EFT must correctly reproduce the classical hydrodynamic equations. ► The SK-EFT must satisfy:

✓ Unitarity constraints:



✓ KMS symmetry:

 $\mathbf{K} h_r(t) = h_r(-t)$ $\mathbf{K} h_a(t) = \left(h_a + i\partial_t h_r\right)(-t)$

)
$$a; h_r, h_a]$$

 Ψ_r : physical dynamical field(s) – Ψ_a : noise dynamical field(s)

(not necessarily the classical field ψ)

Schwinger-Keldysh effective field theory

Schwinger-Keldysh effective field theory (SK-EFT)

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$$a; h_r, h_a]$$

 Ψ_r : physical dynamical field(s) – Ψ_a : noise dynamical field(s)

(not necessarily the classical field ψ)

Schwinger-Keldysh hydrodynamics 101

There may be multiple SK-EFTs for a hydrodynamic model. Consider ($S = \int dt dx \mathscr{L}$)

Canonical Scheme (Can)

$$\mathscr{L} = -\psi_a \left(\mu(\psi_r) - h_r \right) + \psi_a \frac{i}{\Gamma} \left(\psi_a + i\partial_t \psi_r \right) + h_a \psi_r$$

$$K \psi_r(t) = \psi_r(-t)$$

$$K \psi_a(t) = \left(\psi_a + i\partial_t \psi_r\right)(-t)$$

Not suitable for Model B

 $\psi \equiv \psi_r$

- ➤ The KMS symmetries in the two schemes are physically distinct.*
- Field redefinitions affect the renormalisation structure of physical observables.

*In fact, $K_C \psi_r = K_{GC} \psi_r$, but $K_C \psi_a \stackrel{\text{onshell}}{=} - K_{GC} \psi_a$.





Schwinger-Keldysh hydrodynamics 101

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*In fact, $K_C \psi_r = K_{GC} \psi_r$, but $K_C \psi_a \stackrel{\text{onshell}}{=} - K_{GC} \psi_a$.

 $\partial_t \psi + \Gamma \Big(\mu - h \Big) = 0$ Grand Canonical Scheme (GCan) $\mathscr{L} = \psi(\partial_t \phi_r + h_r) \left(\partial_t \phi_a + h_a \right) + i \phi_a \Gamma \left(\phi_a + i \partial_t \phi_r \right)$ $\psi_a \leftrightarrow \Gamma \phi_a$ $\mathbf{K}\phi_r(t) = -\phi_r(-t)$ $\mathbf{K}\,\phi_a(t) = -\left(\phi_a + i\partial_t\,\phi_r\right)(-t)$ $u(\psi_r) \leftrightarrow \partial_t \phi_r + h_r$ $\mu(\psi) \equiv \partial_t \phi_r + h_r$

One or both SK-EFT schemes may be incompatible with hydrostatics due to interactions.







Outline

- Hydrostatic compatibility
- Schwinger-Keldysh hydrodynamics
- > Hydrostatic compatibility at one-loop

- ► BRST ghosts
- ► Lessons and outlook



Stochastic Feynman rules

- > Despite thier differences, the two SK-EFT schemes are qualitatively similar.
- ► Free propagators:

$$\longrightarrow \sim \frac{1}{\Omega - i\omega}$$

Pole(s) only at $\text{Im}\,\omega < 0$

► Interactions:*



► These reproduce the classical retarded and symmetric correlation functions at tree-level.

*There are several other interactions involving background field insertions, which we do not explicitly mention here.

$$\longrightarrow \qquad \sim \frac{1}{\left(\Omega - i\omega\right)\left(\Omega + i\omega\right)}$$

$$---- \Psi_r$$

$$\Omega_{(A)} \equiv (a_2 + \gamma \mathbf{k}^2)$$
$$\Omega_{(B)} \equiv (a_2 + \gamma \mathbf{k}^2)$$

Pole(s) at both $\text{Im} \omega < 0$ and $\text{Im} \omega > 0$







Non-unitary diagrams and GGL prescription

► The non-unitary diagrams:





► What went wrong? Requiring $S|_{h_a, \Psi_a \to 0} = 0 \implies \mathscr{Z}|_{h_a \to 0} = 0$ beyond tree-level.



$$G^{\text{ret}}(t - t', \mathbf{x} - \mathbf{x}') \propto \Theta(t - t')$$



Non-unitary diagrams and GGL prescription

► The non-unitary diagrams:





- ► What went wrong? Requiring $S|_{h_a, \Psi_a \to 0} = 0 \neq 0$
- ► Quick fix: Regularise the retarded propagator (GGL prescription) [Gao, Glorioso, Liu 2018]



Poles of
$$G^{\text{ret}}(\omega, \mathbf{k})$$
 lie at $\text{Im}\,\omega < 0$

$$G^{\text{ret}}(t - t', \mathbf{x} - \mathbf{x}') \neq \Theta(t - t')$$

$$\Rightarrow \mathscr{Z}|_{h_a \to 0} = 0$$
 beyond tree-level.

$$\implies (1 + 1/M \partial_t)^p \partial_t \psi + \Gamma \left(\mu(\psi) - h \right) =$$

 \implies retarded loops vanish



Non-unitary diagrams and GGL prescription

► The non-unitary diagrams:





- > What went wrong? Requiring $S|_{h_a, \Psi_a \to 0} = 0 =$
- Quick fix: Regularise the retarded propagator (GGL prescription) [Gao, Glorioso, Liu 2018]

 $\sim \frac{1}{\Omega - i\omega \left(1 - i\omega/M\right)^p}$

> Caveat: Im $S \neq 0$: $i\psi_a \frac{1}{\Gamma} \left(1 - \frac{p(p-1)}{2M^2}\omega^2 + ...\right)$

*Analogous problem arises in relativistic hydrodynamics in BDNK frame. [Jain, Kovtun 2023] [Mullins et al. 2023]

Poles of
$$G^{\text{ret}}(\omega, \mathbf{k})$$
 lie at $\text{Im}\,\omega < 0$

$$G^{\text{ret}}(t - t', \mathbf{x} - \mathbf{x}') \neq \Theta(t - t')$$

$$\Rightarrow \mathscr{Z}|_{h_a \to 0} = 0 \text{ beyond tree-level.}$$

$$\iff \left(1 + \frac{1}{M}\partial_t\right)^p \partial_t \psi + \Gamma\left(\mu(\psi) - h\right) =$$

 \implies retarded loops vanish

$$\psi_a \quad i\phi_a \Gamma\left(1 - \frac{p}{\Omega M}\omega^2 + \dots\right)\phi_a$$

(dictated by KMS)







()



One-loop results and long-time tails



► Cutoff-independent non-analytic contributions ($\gamma \rightarrow 0, d = 3$):

$$G^{\text{ret}}(\omega, \mathbf{k})_{(A)} = \frac{\Gamma_0}{\Omega - i\omega} + \mathcal{O}(\Lambda^3)$$
$$G^{\text{ret}}(\omega, \mathbf{k})_{(B)} = \frac{\sigma_0 \mathbf{k}^2}{D \mathbf{k}^2 - i\omega} - \frac{\sigma_0^2 \mathbf{k}^4}{\left(D \mathbf{k}^2 - i\omega\right)^2} \left(\frac{a_3}{a_2} + \frac{\sigma_1}{\sigma_0}\right)$$

$$\mu(\psi) = \left(a_2 - \gamma \nabla^2\right)\psi + \frac{1}{2}a_3\psi^2 + \frac{1}{2}(\psi) = \Gamma_0 + \Gamma_1\psi + \frac{1}{2}\Gamma_2\psi^2$$
$$\sigma(\psi) = \sigma_0 + \sigma_1\psi + \frac{1}{2}\sigma_2\psi^2$$
$$\Omega \equiv 0$$
$$D \equiv 0$$



Long-Time Tails

Hydrodynamic modes decay polynomially rather than exponentially.

[Alder, Wainwright 1970] [De Schepper, Van Beyeren, Ernst 1974] [Forster, Nelson, Stephen 1977] [Arnold, Yaffe 1997] [Kovtun, Yaffe 2003] [Chen-Lin, Delacretaz, Hartnoll 2018]



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$$G^{\text{ret}}(\omega, \mathbf{k})_{(A)} = \frac{\Gamma_0}{\Omega - i\omega} + \mathcal{O}(\Lambda^3)$$

$$G^{\text{ret}}(\omega, \mathbf{k})_{(B)} = \frac{\sigma_0 \mathbf{k}^2}{D \mathbf{k}^2 - i\omega} - \frac{\sigma_0^2 \mathbf{k}^4}{\left(D \mathbf{k}^2 - i\omega\right)^2} \left(\frac{a_3}{a_2} + \frac{\sigma_1}{\sigma_0}\right)^2 \frac{i\omega}{32\pi D} \sqrt{\mathbf{k}^2 - \frac{2i\omega}{D}} + \mathcal{O}(\Lambda^3)$$

Weak hydrostatic compatibility:

$$G^{\rm ret}(\omega=0,$$

*In the absence of spontaneous symmetry breaking.

$$\mu(\psi) = \left(a_2 - \gamma \nabla^2\right)\psi + \frac{1}{2}a_3\psi^2 + \frac{1}{2}(\psi) = \Gamma_0 + \Gamma_1\psi + \frac{1}{2}\Gamma_2\psi^2$$
$$\sigma(\psi) = \sigma_0 + \sigma_1\psi + \frac{1}{2}\sigma_2\psi^2$$
$$\Omega \equiv a_0$$
$$D \equiv a_0$$

[AJ, Kovtun, Ritz, Shukla 2020]

Long-Time Tails

Hydrodynamic modes decay polynomially rather than exponentially.

[Alder, Wainwright 1970] [De Schepper, Van Beyeren, Ernst 1974] [Forster, Nelson, Stephen 1977] [Arnold, Yaffe 1997] [Kovtun, Yaffe 2003] [Chen-Lin, Delacretaz, Hartnoll 2018]



Hydrostatic compatibility

► The *correct* hydrostatic compatible results:

$$G^{\text{ret}}(\omega, \mathbf{k})_{(A)} = \frac{\Gamma_0}{\Omega - i\omega} - \frac{\Gamma_0^2}{(\Omega - i\omega)^2} \left[\frac{a_4}{a_2} - \frac{2\Omega}{2\Omega - i\omega} \left(\frac{a_3}{a_2} + \frac{i\omega}{\Omega} \frac{\Gamma_1}{\Gamma_0} \right)^2 + \frac{i\omega}{\Omega} \left(\frac{\Gamma_2}{\Gamma_0} - \frac{2\Gamma_1^2}{\Gamma_0^2} \right) \right] \frac{\Lambda^3}{12\pi^2} + \dots$$

$$G^{\text{ret}}(\omega, \mathbf{k})_{(B)} = \frac{\sigma_0 \mathbf{k}^2}{D \mathbf{k}^2 - i\omega} - \frac{\sigma_0^2 \mathbf{k}^4}{(D \mathbf{k}^2 - i\omega)^2} \left[\left(\frac{a_4}{a_2} - \frac{a_3^2}{a_2^2} + \frac{\sigma_2}{\sigma_0} \frac{i\omega}{D \mathbf{k}^2} \right) \frac{\Lambda^3}{12\pi^2} + \frac{i\omega}{D} \left(\frac{a_3}{a_2} + \frac{\sigma_1}{\sigma_0} \right)^2 \left(\frac{1}{32\pi} \sqrt{\mathbf{k}^2 - \frac{2i\omega}{D}} - \frac{\Lambda}{8\pi^2} \right) \right] + \dots$$

$$\xrightarrow{\omega \to 0} \qquad G^{\text{eqb}}(\mathbf{k}) = \frac{1}{a_2} - \frac{1}{a_2^2} \left(\frac{a_4}{a_2} - \frac{a_3^2}{a_2^2} \right) \frac{\Lambda^3}{12\pi^2} + \dots$$
The SK-EFT results (GGL prescription) differ by:
$$G^{\text{ret}}(\omega, \mathbf{k})_{(A)} \sim \begin{cases} (\text{Can}): 0 \\ (\text{GCan}): \frac{-2\Gamma_0^2}{(\Omega - i\omega)^2} \left(\frac{\Gamma_2}{\Gamma_0} - \frac{\Gamma_1^2}{\Gamma_0^2} \right) \frac{\Lambda^3}{12\pi^2} - G^{\text{ret}}(\omega, \mathbf{k})_{(B)} \sim \begin{cases} (\text{Can}): n/a \\ (\text{GCan}): \frac{-\sigma_0^2 \mathbf{k}^4}{\sigma_0 \sigma_0} \frac{a_3}{12\pi^2} + \dots \end{cases}$$





- hydrodynamics.

In case I made you sleep...

Stochastic fluctuations induce loop corrections in retarded functions, which can be systmatically computed using Schwinger-Keldysh

The naive SK-EFT results are incorrect because of non-unitary diagrams. This can be fixed using the GGL regularisation prescription, at the expense of positivity of symmetric functions.

► There may be multiple SK-EFT models corresponding to the same classical hydrodynamic model.

Hydrostatic-compatibility with GGL regularisation:

	Can Scheme (GGL)	GCan Scheme (GGL)	
Model A		×	
Model B		×	

Outline

- Hydrostatic compatibility
- Schwinger-Keldysh hydrodynamics

Hydrostatic compatibility at one-loop

► BRST ghosts

► Lessons and outlook

BRST ghosts

► The GGL prescription gives correct hydrostatic-compatible results in the "Can" scheme, but not in the "GCan" scheme.

► However, the "Can" scheme does not apply to Model B. Therefore, the GGL prescription does not yield *any* hydrostatic-compatible SK-EFT for Model B (i.e. for conserved degrees of freedom).

➤ The proper way to address these issues is introducing BRST ghosts, which systmatically cancel the unphysical contributions arising from non-unitary diagrams.

[Arenas, Barci 2010] [Haehl, Loganayagam, Rangamani 2016] [Gao, Liu 2017] [Jensen, Pinzani-Fokeeva, Yarom 2017]

Ghosts in MSR path integral

► Technically, the MSR generating functional involves a functional determinant, which gives rise to ghosts:

$$\mathcal{Z}[h_r, h_a] = \int \mathcal{D}\theta \, \mathcal{D}\psi_r \left[\det\left[\frac{\delta(E+f\theta)}{\delta\psi_r}\right] \right] \delta[E+f\theta] \exp\left(i\int_x \frac{i}{4}\theta^2 + h_a\psi_r\right) \\ \int \mathcal{D}c_r \, \mathcal{D}c_a \exp\left(i\int_x c_a \frac{\delta(E+f\theta)}{\delta\psi_r}c_r\right) \\ \text{pariant under BRST symmetry:} \\ Q\psi_r = \epsilon c_r \qquad Q c_a = \epsilon \psi_a \qquad \Longrightarrow \qquad \mathcal{Z}|_{h_a \to 0} = 0$$

➤ The theory is inv

$$[h_{a}] = \int \mathscr{D}\theta \, \mathscr{D}\psi_{r} \left[\det \left[\frac{\delta(E+f\theta)}{\delta\psi_{r}} \right] \right] \delta[E+f\theta] \exp \left(i \int_{x} \frac{i}{4} \, \theta^{2} + h_{a} \psi_{r} \right) \right]$$

$$\int \mathscr{D}c_{r} \, \mathscr{D}c_{a} \exp \left(i \int_{x} c_{a} \frac{\delta(E+f\theta)}{\delta\psi_{r}} c_{r} \right)$$

$$f \text{ under BRST symmetry:}$$

$$Q\psi_{r} = \epsilon c_{r} \qquad Q c_{a} = \epsilon \psi_{a} \qquad \Longrightarrow \qquad \mathscr{Z}|_{h_{a} \to 0} = 0$$

► The MSR ghost sector *does not* necessarily furnish a KMS symmetry. ► The ghost sector is ambiguous^{*}: it changes if we use ϕ_r (with $\mu(\psi_r) = \partial_t \phi_r + h_r$) as a degree of freedom.

*This ambiguity is related to the well-known ambiguity in discretising stochastic Langevin equations.

We also need to introduce "background ghost fields" that mix with physical/noise background fields under BRST transformations.

Anticommuting Ghost Fields: $C_{r,a} = (c_{r,a}, d_{r,a})$

$$f_{a}(t) = \pm \left(\Psi_{a} + i\partial_{t}\Psi_{r}\right)(-t)$$

$$f_{a}(t) = \pm C(-t)$$

[Arenas, Barci 2010] [Haehl, Loganayagam, Rangamani 2016] [Gao, Liu 2017] [Jensen, Pinzani-Fokeeva, Yarom 2017]

► Propagators:

► Interactions:

Hydrostatic compatibility

► The SK-EFT results (ghost prescription) deviate from the hydrostatic-compatible results by:

$$G^{\text{ret}}(\omega, \mathbf{k})_{(A)} \sim \begin{cases} (\text{Can}): \frac{\Gamma_0^2}{(\Omega - i\omega)^2} \left(\frac{\Gamma_2}{\Gamma_0}\right)^2 \\ (\text{GCan}): 0 \end{cases}$$

Model A Model B

Unfortunately, neither of the regularisation prescriptions guarantee hydrostatic-compatibility.

In case I made you sleep, again...

► The proper mechanism to cancel the non-unitary diagrams is by introducing BRST ghost fields.

► BRST symmetry combined with KMS symmetry leads to an emergent supersymmetry is SK-EFTs.

► Hydrostatic-compatibility with GGL and ghost regularisations:

Can Scheme (GGL)	GCan Scheme (GGL)	Can Scheme (ghosts)	GCan Scheme (ghosts)
	X	X	
	×		\checkmark

Outline

- Hydrostatic compatibility
- Schwinger-Keldysh hydrodynamics

- Hydrostatic compatibility at one-loop
- ► BRST ghosts
- ► Lessons and outlook

Lessons

Hopefully, this continues to hold for full hydrodynamics with conserved energy and momentum degrees of freedom.

Hydrostatic compatibility of Schwinger-Keldysh hydrodynamics is not automatic. It depends on the regularisation prescription implemented to eliminate the unphysical non-unitary diagrams.

Circumventing the need for ghosts using the GGL prescription might cause violations of unitarity in symmetric correlation functions.

There may be multiple Schwinger-Keldysh models corresponding to the same classical hydrodynamic model.

► What fares best: Grand Canonical (GCan) scheme with BRST ghost regularisation is hydrostatic compatible and works for both Model A and Model B.

Wishful thinking!

Food for thought

► The "GCan" scheme breaks down near critical points

 $\mu(\psi)$ =

while "Can" scheme only works for Model A. Is there a consistent hydrostatic-compatible SK-EFT for Model B? How does this fit with conventional stochastic hydrodynamics?

Can we run real-time Wilsonian RG on SK-EFTs? Will need non-Gaussian stochastic transport. [Jain, Kovtun 2020]

 Can we extend the BRST ghost structure to out-of-time-ordered (OTO) SK-EFTs?
 Higher-N emergent supersymmetry?
 Interesting repucursions for Quantum Chaos?

$$= \frac{\delta}{\delta\psi} \int_{\mathbf{X}} \left(\frac{1}{2} \partial^{i}\psi \partial_{i}\psi + \frac{a_{2}}{2} \psi^{2} + \frac{a_{4}}{24} \psi^{4} \right) \qquad \qquad \mu(\psi) = -\frac{\partial_{i} \partial^{i} \psi + \frac{\partial_{i} \partial^{i} \psi}{\partial_{i} \psi} + \frac{\partial_{i} \partial^{i} \psi}{\partial_{i$$

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THANK YOU

References

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